

The four subspaces as orthogonal complements

Calculating basis for an orthogonal complement - How? Calculating orthonormal basis for an orthogonal complement - How?

$A\bar{x} = \bar{b}$ has a solution, \bar{b} is in the column space of A , if and only if $H\bar{b} = \bar{0}$, \bar{b} is in the nullspace of H . What's in H ? Why?

If $A\bar{x} = \bar{b}$ has a solution for a given \bar{b} , then there is always a (unique) solution in the row space of A . How does that work?

Dimensions of the 4 subspaces.

Given an $m \times n$ matrix A , and a vector \bar{x} in R^n , we can write $\bar{x} = \bar{x}_{\text{row}} + \bar{x}_{\text{null}}$, where the vectors on the right are in the row and null spaces of A respectively. How is \bar{x}_{row} related to \bar{x} via projection? How could you find matrices P, Q such that $\bar{x}_{\text{row}} = P\bar{x}$ and $\bar{x}_{\text{null}} = Q\bar{x}$.

The null space of A is the same as the null space of $A^T A$. How does that work?

Orthogonal projections:

Onto a one-dimensional subspace

Onto a subspace.

How to calculate a projection, how to calculate the projection matrix, how to identify a projection (what is the definition?).

Projection when you have an orthonormal basis Q . $\bar{p} = QQ^T \bar{x}$ why?

What is the significance of writing $\bar{b} = \bar{p} + (\bar{b} - \bar{p})$? We have decomposed \bar{b} into a sum of two vectors that belong to what subspaces?

Least-squares solution of a linear system $A\bar{x} = \bar{b}$. The "solution" \bar{x} has the property that $A\bar{x} = \text{what?}$

The normal equations - what are they, where do they come from, what do they express?

Matrix Q with orthonormal columns - $Q^T Q = I$, preserves dot products

Gram-Schmidt, leads to $A = QR$ decomposition. Since $\text{col}(A) = \text{col}(Q)$ by construction, the normal equations for calculating the least squares solution of $A\bar{x} = \bar{b}$ can be alternatively written $Q^T(\bar{b} - A\bar{x}) = \bar{0}$, $Q^T \bar{b} = Q^T QR\bar{x}$ so $Q^T \bar{b} = R\bar{x}$. Of course \bar{p} itself is simply $\bar{p} = QQ^T \bar{b}$.

Determinants:

Basic properties, elimination steps and the value of the determinant.

Evaluating a determinant using successive elimination and expansion.

What the determinant determines

$$\det(AB) = \det A \det B, \det A^T = \det A$$

Total expansion of a determinant: the big formula

$$A = \det \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix} \quad \text{In the expansion of } \det A = \dots + (\quad) bfg + \dots \text{ does } + \text{ or } - \text{ go in the}$$

parentheses?

Expansion (across rows or down columns) by cofactors

The cofactor matrix C and its property $AC^T = (\det A)I$

Inverses using the cofactor matrix. Cramer's rule.