

Hamilton Circuits and Essential Girth of Claw Free Graphs

Zhengke Miao, Xiaofeng Wang & Cun-Quan Zhang

Graphs and Combinatorics

ISSN 0911-0119

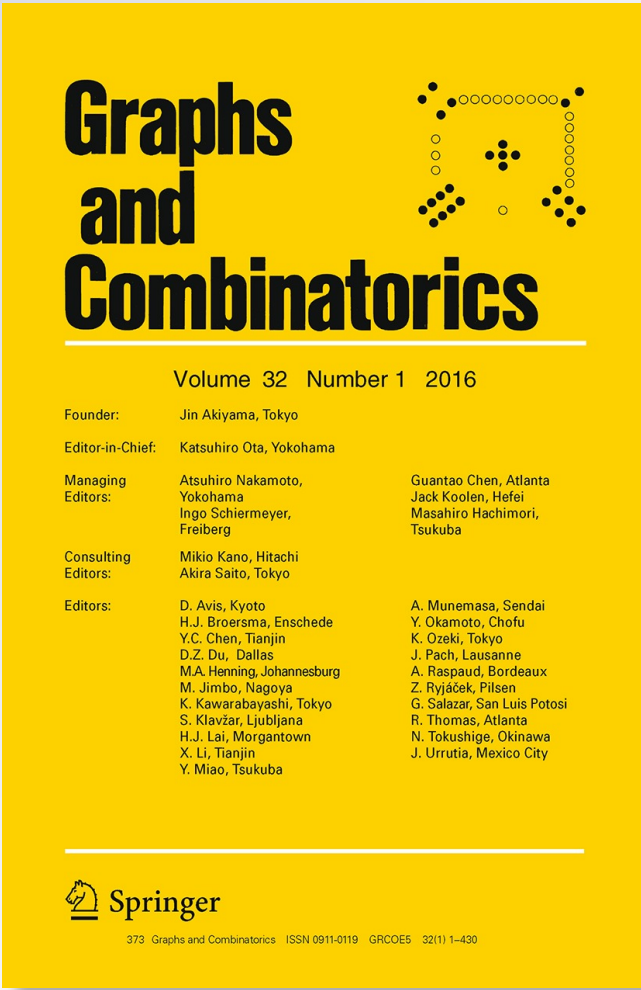
Volume 32

Number 1

Graphs and Combinatorics (2016)

32:311-321

DOI 10.1007/s00373-015-1559-9



**Graphs
and
Combinatorics**

Volume 32 Number 1 2016

Founder: Jin Akiyama, Tokyo

Editor-in-Chief: Katsuhiro Ota, Yokohama


Managing Editors: Atsuhiko Nakamoto, Yokohama
Ingo Schiermeyer, Freiberg

Consulting Editors: Mikio Kano, Hitachi
Akira Saito, Tokyo

Editors: D. Avis, Kyoto
H.J. Broersma, Enschede
Y.C. Chen, Tianjin
D.Z. Du, Dallas
M.A. Henning, Johannesburg
M. Jimbo, Nagoya
K. Kawarabayashi, Tokyo
S. Klavžar, Ljubljana
H.J. Lai, Morgantown
X. Li, Tianjin
Y. Miao, Tsukuba

Guantao Chen, Atlanta
Jack Koolen, Hefei
Masahiro Hachimori, Tsukuba

A. Munemasa, Sendai
Y. Okamoto, Chofu
K. Ozeki, Tokyo
J. Pach, Lausanne
A. Raspaud, Bordeaux
Z. Ryjáček, Pilsen
G. Salazar, San Luis Potosi
R. Thomas, Atlanta
N. Tokushige, Okinawa
J. Urrutia, Mexico City

 Springer

373 Graphs and Combinatorics ISSN 0911-0119 GRCOE5 32(1) 1-430

Your article is protected by copyright and all rights are held exclusively by Springer Japan. This e-offprint is for personal use only and shall not be self-archived in electronic repositories. If you wish to self-archive your article, please use the accepted manuscript version for posting on your own website. You may further deposit the accepted manuscript version in any repository, provided it is only made publicly available 12 months after official publication or later and provided acknowledgement is given to the original source of publication and a link is inserted to the published article on Springer's website. The link must be accompanied by the following text: "The final publication is available at link.springer.com".

Hamilton Circuits and Essential Girth of Claw Free Graphs

Zhengke Miao · Xiaofeng Wang ·
Cun-Quan Zhang

Received: 22 August 2014 / Revised: 7 January 2015 / Published online: 7 March 2015
© Springer Japan 2015

Abstract Let G be a $K_{1,3}$ -free graph. A circuit of G is essential if it contains a non-locally connected vertex v and passes through both components of $N(v)$. The essential girth of G , denoted by $g_e(G)$, is the length of a shortest essential circuit. It can be seen easily that, by Ryjáček closure operation, the essential girth of G is closely related to the girth of H where H is the Ryjáček closure of G and is a line graph. A generalized net, denoted by N_{i_1, i_2, i_3} , is a graph obtained from a triangle C_3 and three disjoint paths $P_{i_\mu+1}$ ($\mu = 1, 2, 3$), by identifying each vertex v_μ of $C_3 = v_1 v_2 v_3 v_1$ with an end vertex of the path $P_{i_\mu+1}$, for every $\mu = 1, 2, 3$. In this paper, we prove that every 2-connected $\{K_{1,3}, N_{1,1, g_e(G)-4}\}$ -free (and $\{K_{1,3}, N_{1,0, g_e(G)-3}\}$ -free) graph G contains a Hamilton circuit. With the additional parameter g_e , these results extend some earlier theorems about Hamilton circuits in $\{K_{1,3}, N_{a,b,c}\}$ -free graphs (for some small integers a, b and c).

Partially supported by an NSF-China Grant: NSFC 11171288 for Zhengke Miao, and partially supported by an NSF Grant DMS-1264800 and NSA Grants H98230-12-1-0233 and H98230-14-1-0154 for Cun-Quan Zhang.

Z. Miao
School of Mathematics and Statistics, Jiangsu Normal University,
Jiangsu 221116, China
e-mail: zkmiao@jsnu.edu.cn

X. Wang
Department of Mathematics and Actuarial Science, Indiana University Northwest,
Gary, IN 46408, USA
e-mail: wang287@iun.edu

C.-Q. Zhang (✉)
Department of Mathematics, West Virginia University, Morgantown,
WV 26506, USA
e-mail: cqzhang@math.wvu.edu

Keywords Claw-free graph · Net-free graph · Hamilton circuit · Forbidden pairs · Essential girth · Closure operation

1 Introduction

Let G be a graph. If a subgraph G' of G contains all edges $xy \in E(G)$ with $x, y \in V(G')$, then G' is called an induced subgraph of G . For a given graph H , we say that G is H -free if G does not contain an induced subgraph isomorphic to H .

A claw is the complete bipartite graph $K_{1,3}$. A simple graph G is claw-free if it has no induced subgraph $K_{1,3}$.

Let P_i be the path on i vertices, and C_i the circuit on $i \geq 3$ vertices. We adopt the definition of generalized net in [4]. A generalized net, denoted by N_{i_1, i_2, i_3} , is a graph obtained from a triangle C_3 and three disjoint paths $P_{i_\mu+1}$ ($\mu = 1, 2, 3$), by identifying each vertex v_μ of $C_3 = v_1 v_2 v_3 v_1$ with an end vertex of the path $P_{i_\mu+1}$, for every $\mu = 1, 2, 3$.

We call a graph G hamiltonian if it contains a Hamilton circuit, i.e., a circuit containing all its vertices. Regarding a graph to be hamiltonian, the following theorem is one of the earliest results in this subject of forbidden pairs.

Theorem 1.1 [6] *Let G be a $\{K_{1,3}, N_{1,1,1}\}$ -free graph. If G is 2-connected, then G is hamiltonian.*

And it is followed by some other forbidden pairs.

Theorem 1.2 [3] *If G is a 2-connected $\{K_{1,3}, P_6\}$ -free graph, then G is hamiltonian.*

Theorem 1.3 [10] *If G is a 2-connected $\{K_{1,3}, N_{0,0,2}\}$ -free graph, then G is hamiltonian.*

Theorem 1.4 [1] *If G is a 2-connected $\{K_{1,3}, N_{0,1,2}\}$ -free graph, then G is hamiltonian.*

Theorem 1.5 [7] *If G is a 2-connected $\{K_{1,3}, N_{0,0,3}\}$ -free graph, then G is hamiltonian.*

Faudree and Gould [8] later refined this approach by the following classification theorem.

Theorem 1.6 [8] *Let G be a 2-connected, $\{K_{1,3}, S\}$ -free graph. Then G is hamiltonian if S is one of $C_3, N_{0,0,1}, N_{0,0,2}, N_{0,0,3}, N_{0,1,1}, N_{1,1,1}, N_{0,1,2}$ (see Fig. 1).*

The following is one of the major open problems in this subject.

Conjecture 1.1 [14] *Every 4-connected claw-free graph is hamiltonian.*

There are other related results about forbidden pairs or local structures for Hamilton circuits in claw-free graphs regarding Conjecture 1.1, such as [2, 5, 12, 15]. Lai et al. [13] and Fujisawa [9] recently showed some results for the forbidden pairs including a generalized net graph.

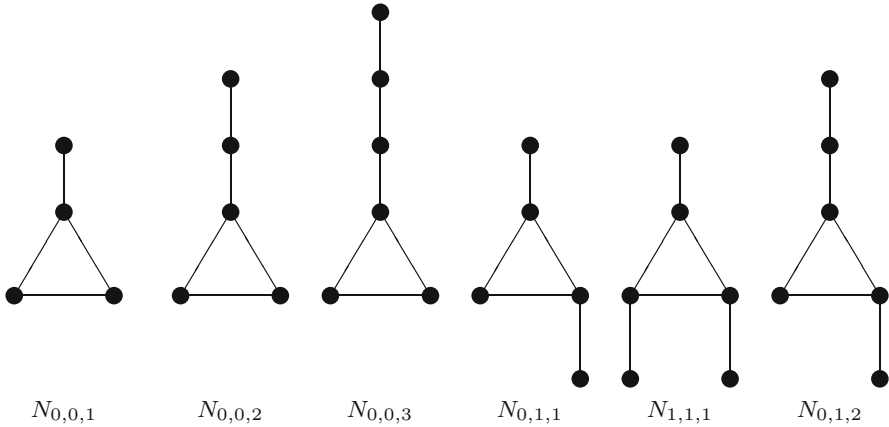


Fig. 1 $N_{0,0,1}$, $N_{0,0,2}$, $N_{0,0,3}$, $N_{0,1,1}$, $N_{1,1,1}$ and $N_{0,1,2}$

Theorem 1.7 [13] *If G is a 3-connected $\{K_{1,3}, N_{0,0,8}\}$ -free graph, then G is hamiltonian.*

Theorem 1.8 [9] *If G is a 3-connected $\{K_{1,3}, N_{0,0,9}\}$ -free graph, then G is hamiltonian unless G is the line graph of Q^* , where Q^* is obtained from the Petersen graph by adding one pendent edge to each vertex.*

For a graph G and $v \in G$, denote the neighbor of v to be $N(v) = \{u \in V(G) : u \text{ is adjacent to } v\}$.

Definition 1.1 For a claw free graph $G = (V, E)$, a vertex v is locally connected if the induced subgraph $G[N(v)]$ is connected. And denote $V_{lc} = \{v \in V(G) : v \text{ is locally connected}\}$, $V_{nlc} = \{v \in V(G) : v \text{ is not locally connected}\}$.

It is evident that if v is not locally connected, then the induced subgraph $G[N(v)]$ consists of two cliques Q_1^v, Q_2^v (see Lemma 2.2).

Definition 1.2 Let G be a claw-free graph. A circuit $C = v_1 \dots v_r v_1$ of G is essential if it contains a non-locally connected vertex v_i and $v_{i-1}v_{i+1} \notin E(G)$.

Notice that the essential circuit C , with a non-locally connected vertex v_i , should pass through both clique components of $N(v_i)$ for otherwise there will be an edge between v_{i-1} and v_{i+1} .

Definition 1.3 The essential girth of a claw-free graph, denoted by $g_e(G)$, is the length of a shortest essential circuit.

Furthermore, it can be seen easily that, by Ryjáček closure operation [16], the essential girth of G is closely related to the girth of H where H is the line graph of the Ryjáček closure of G .

Here is the main theorem of this paper.

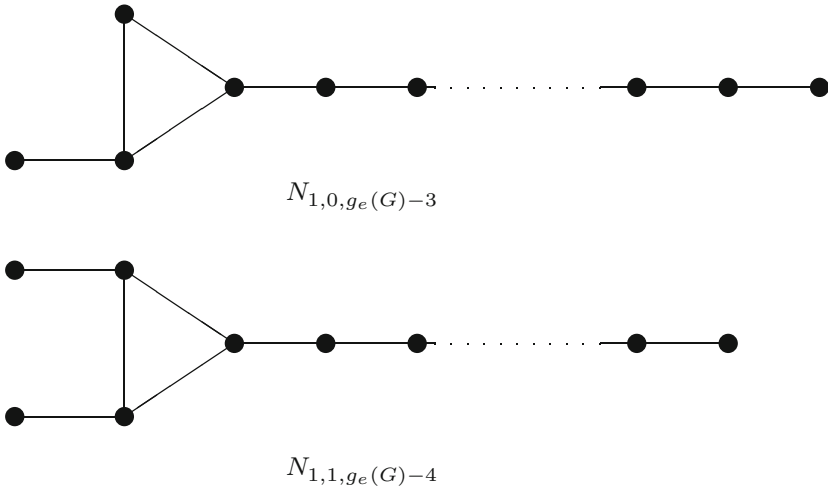


Fig. 2 $N_{1,0,g_e(G)-3}$ and $N_{1,1,g_e(G)-4}$

Theorem 1.9 (1) *If a 2-connected graph G is claw-free and $N_{1,1,g_e(G)-4}$ -free, then G contains a Hamilton circuit.*

(2) *If a 2-connected graph G is claw-free and $N_{1,0,g_e(G)-3}$ -free, then G contains a Hamilton circuit (see Fig. 2).*

With the additional parameter g_e , these results extend some earlier theorems about Hamilton circuits in $\{K_{1,3}, N_{a,b,c}\}$ -free graphs (for some small integers a, b and c).

2 Preliminary Results and Lemmas

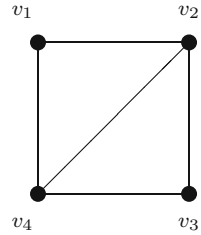
In this section, we present some early results and useful lemmas for the preparation of the proof of Theorem 1.9.

If H is a graph, then the *line graph* of H , denoted by $L(H)$, is the graph on vertex set $E(H)$ in which two vertices are adjacent if and only if their corresponding edges in H share an end vertex. A graph G is a line graph if it is isomorphic to $L(H)$ for some graph H . Note that line graphs are claw-free.

We say a subgraph is *even* if the degree of each vertex in the subgraph is even. And a *dominating connected even subgraph* of a graph H is a connected even subgraph such that every edge of H has at least one end vertex contained in the connected even subgraph. There is an intimate relationship between dominating connected even subgraph in H and Hamilton circuit in $L(H)$, a result due to Harary and Nash-Williams [11] that is known since the 1960s.

Lemma 2.1 [11] *Let H be a graph of size at least three. The line-graph $L(H)$ has a Hamilton circuit if and only if H has a dominating connected even subgraph.*

Fig. 3 $K_4 - \{e\}$



A closure operation is to add edges to turn $G[N(v)]$ into a complete graph for every locally connected vertex $v \in V(G)$ until it is impossible to add any more edges.

The following theorem due to Ryjáček [16] provides an opportunity to translate questions on hamiltonicity of claw-free graphs to questions on hamiltonicity of line graphs by using the concept of closure operation.

Theorem 2.1 [16] *Let G be a claw-free graph. Then (1) G has a Hamilton circuit if and only if the closure $cl(G)$ has a Hamilton circuit. (2) Furthermore, $cl(G)$ is the line graph $L(H)$ for some graph H .*

The following is a well-known folklore result for claw-free graphs.

Lemma 2.2 *Let G be a claw-free graph. For $v \in V_{nlc}$, the induced subgraph $G[N(v)]$ consists of two disjoint cliques Q_1^v, Q_2^v . Furthermore, if the non-locally connected vertex v is contained in a vertex-cut T with components R_1, R_2 of $G - T$, then $Q_i^v \subseteq R_i \cup T$ for $i = 1, 2$.*

Lemma 2.3 *Let v be a non-locally connected vertex of a claw-free graph G with components Q_1^v, Q_2^v of $G[N(v)]$. Let $C = vx_1, \dots, x_rv$ be a circuit of G containing v and $x_1 \in Q_1^v, x_r \in Q_2^v$. If each x_i is locally connected in G for every $i \in \{2, \dots, r-1\}$, then v is locally connected in the closure $cl(G)$.*

Proof We first claim that, for each $i, j \in \{1, \dots, r\}$, there is an edge $x_i x_j$ in the closure $cl(G)$.

We prove this claim by induction on $|j - i|$.

The claim is true for $|j - i| = 1$.

Now consider $|j - i| \geq 2$. Let $1 \leq i < j \leq r$. The vertex x_{i+1} remains locally connected in $cl(G)$ since the closure only adds edges. Notice that $x_j \in N_{cl(G)}(x_{i+1})$ by the induction hypothesis. Then both $x_i, x_j \in N_{cl(G)}(x_{i+1})$, so the edge $x_i x_j$ must appear in $cl(G)$. This finishes the proof of the claim.

By the above claim, $x_1 x_r \in E(cl(G))$, which joins Q_1^v, Q_2^v . Thus, $N_{cl(G)}(v)$ induces a connected subgraph in $cl(G)$, so v is locally connected in the closure $cl(G)$. \square

Lemma 2.4 *Let G be a claw-free graph. If Q is an induced subgraph of G isomorphic to $K_4 - \{e\}$ (see Fig. 3) where $V(K_4) = \{v_1, \dots, v_4\}$ and $e = v_1 v_3$, then both v_2, v_4 are locally connected vertices.*

Proof If v_2 is not locally connected, by Lemma 2.2, vertices v_1, v_3, v_4 are contained in the same clique, which contradicts that v_1v_3 is a missing edge in G . Similarly v_4 is also locally connected. \square

Lemma 2.5 *Let G be a claw-free graph with the essential girth $g_e(G) \geq 5$, if $C = v_1v_2v_3v_4v_1$ is an induced 4-circuit of G , then all v_i are locally connected vertices for $1 \leq i \leq 4$.*

Proof Suppose that v_1 is not locally connected. By the definition of the essential girth $g_e(G)$ and the assumption that $g_e(G) \geq 5$, both vertices v_2, v_4 are in the same component Q_i^v for some $i \in \{1, 2\}$. And by Lemma 2.2, $v_2v_4 \in E(G)$ which contradicts that C is an induced circuit, so v_1 is locally connected. Similar arguments can be applied to v_2, v_3 , and v_4 . \square

Lemma 2.6 *Let $T = \{u, v\}$ be a cut of a 2-connected claw-free graph G , then*

- (i) *either both u and v are non-locally connected in G*
- (ii) *or both u and v are locally connected, and adjacent to each other.*

Proof Suppose that at least one of $\{u, v\}$, say u , is locally connected in G . Let R_1, R_2 be two components of $G - T$. Since u is locally connected in G , let P be a shortest path contained in $G[N(u)]$ joining $R_1 \cap N(u)$ and $R_2 \cap N(u)$. It is obvious that $P = x_1vx_2$ where $x_i \in R_i \cap N(u)$ ($i = 1, 2$). The subgraph $G[u, v, x_1, x_2]$ is isomorphic to $K_4 - \{x_1x_2\}$. By Lemma 2.4, v is also locally connected. \square

3 Proof of the Main Theorem

In this section, we present the proof of Theorem 1.9.

We prove this result by contradiction. Let G be a counterexample to Theorem 1.9 with $|V(G)| + |E(G)|$ as small as possible. This means G is a 2-connected, claw-free and either $N_{1,1,g_e(G)-4}$ -free or $N_{1,0,g_e(G)-3}$ -free graph. For $g_e(G) = 4, 5$, the theorem is already proved in Theorem 1.6, so for the rest part of the proof, we will assume that (*) $g_e(G) \geq 6$.

If every vertex in the closure $cl(G)$ is locally connected, then $cl(G)$ is a complete graph. By Ryjáček's closure Theorem (Theorem 2.1), $cl(G)$ has a Hamilton cycle.

Thus, we may assume that there exist non-locally connected vertices in $cl(G)$.

Claim 3.1 *For every non-locally connected vertex v of $cl(G)$, v is contained in a 2-vertex cut of G .*

Proof Let v be a non-locally connected vertex of $cl(G)$ (and non-locally connected in G , as well) and supposed that v is not contained in any 2-vertex cut of G .

By Lemma 2.2, let Q_1^v, Q_2^v be components of $G[N(v)]$. Without loss of generality, let $|Q_2^v| \leq |Q_1^v|$. Let F be the set of edges between v and Q_2^v , that is $F = \{v, Q_2^v\}$. And let

$$W_i = \{x \in V(G) : distance_{(G-F)}(x, v) = i\}.$$

Let r be the smallest integer that $Q_2^v \cap W_r \neq \emptyset$.

Since $G - v$ is 2-connected, there exist two chordless paths $P_1 = x_1 \dots x_{r-1}x_r$, $P_2 = y_1 \dots y_{r-1}y_r$ such that

- (1) $x_i, y_i \in W_i$ for $1 \leq i \leq r$,
- (2) $x_i \neq y_i$ for $2 \leq i \leq r - 1$,
- (3) $x_r \in Q_2^v$.

Notice that by the definition of the essential girth $g_e(G)$, we have $r \geq g_e(G) - 1$. \square

Subclaim 3.1.1 *If $x_i y_{i+1} \in E(G)$ [or, $y_i x_{i+1} \in E(G)$], for some $i: 1 \leq i \leq r - 1$, then $x_i y_i, x_{i+1} y_{i+1} \in E(G)$.*

Proof If $x_{i+1} y_{i+1} \notin E(G)$, then $G[x_i, x_{i-1}, y_{i+1}, x_{i+1}]$ is a claw by the definition of the sets W_i . Hence, $x_{i+1} y_{i+1} \in E(G)$. Symmetrically, $x_i y_i \in E(G)$. \square

Without confusion, let $v = x_0 = y_0$.

For an integer $i \in \{0, \dots, r - 1\}$, the pair $\{i, i + 1\}$ is called a *non-diagonal pair* if $x_i \neq y_i, x_{i+1} \neq y_{i+1}$ and both $x_i y_{i+1}, y_i x_{i+1} \notin E(G)$; the pair $\{i, i + 1\}$ is called a *diagonal pair* if both $x_i y_{i+1}, y_i x_{i+1} \in E(G)$ or $x_i = y_i$ or $x_{i+1} = y_{i+1}$. Note that there may be pairs that are neither.

Subclaim 3.1.2 *For each $i \in \{0, \dots, r - 2\}$,*

- (1) *if $x_{i+1} \neq y_{i+1}$, then $x_{i+1} y_{i+1} \in E(G)$, and*
- (2) *if $\{i, i + 1\}$ is a non-diagonal pair, then $\{i + 1, i + 2\}$ is a diagonal pair.*

Proof This proof is by induction on i .

For $i = 0$, there is nothing to prove for statement (1) since x_1, y_1 are in the clique Q_1^v . Also, there is nothing to prove for statement (2) either, since both $v x_1, v y_1 \in E(G)$ where $v = x_0 = y_0$. In the case that $x_1 = y_1$, to avoid a claw centered at $x_1 = y_1$, we get $x_2 y_2 \in E(G)$.

Assume that there is an integer J ($1 \leq J \leq r - 2$) such that both statements hold for every i with $0 \leq i \leq J - 1$.

The following is the proof of the statements (1) and (2) for $i = J$.

Suppose that $x_{i+1} y_{i+1} \notin E(G)$. By Subclaim 3.1.1, the assumption that $x_{i+1} y_{i+1} \notin E(G)$ implies that both $\{i, i + 1\}$ and $\{i + 1, i + 2\}$ are non-diagonal pairs. The pair $\{i - 1, i\}$ cannot be non-diagonal pair, for otherwise, by inductive hypotheses of statement (2), $\{i, i + 1\}$ cannot be non-diagonal either.

In summary, $x_{i+1} y_{i+1} \notin E(G)$, and, both $\{i, i + 1\}$ and $\{i + 1, i + 2\}$ are non-diagonal pairs. And $\{i - 1, i\}$ is not a non-diagonal pair. Without loss of generality, let $x_{i-1} y_i \in E(G)$. Thus, the subgraph induced by vertices

$$\{v, x_1, \dots, x_r\} - \{x_{i+2}\} + \{y_i, y_{i+1}\}$$

contains a generalized net $N_{1,1,g_e(G)-4}$; and the subgraph induced by vertices

$$\{v, x_1, \dots, x_r\} - \{x_{i+1}\} + \{y_i, y_{i+1}\}$$

contains a generalized net $N_{1,0,g_e(G)-3}$. This is a contradiction and proves the statement (1).

For the statement (2), assume that $\{i, i + 1\}$ is a non-diagonal pair and assume that $x_{i+2} \neq y_{i+2}$. Then $y_{i+1}x_{i+2} \in E(G)$ for otherwise, $G[x_{i+1}, x_i, y_{i+1}, x_{i+2}]$ is a claw. Similarly, $y_{i+2}x_{i+1} \in E(G)$. This proves the statement (2). \square

Subclaim 3.1.3 $\{x_i, y_i\}$ are locally connected vertices of G for each $i = 2, \dots, r - 1$.

Proof Consider $i \in \{2, \dots, r - 1\}$. By Lemma 2.5, we may assume that neither $\{i - 1, i\}$ nor $\{i, i + 1\}$ is a non-diagonal pair. Hence, let $u' \in \{x_{i-1}, y_{i-1}\} \cap N(x_i) \cap N(y_i)$ and $u'' \in \{x_{i+1}, y_{i+1}\} \cap N(x_i) \cap N(y_i)$. The subgraph of G induced by $\{u', u'', x_i, y_i\}$ is $K_4 - e$. By Lemma 2.4, both x_i, y_i are locally connected. \square

Proof Thus, we have a circuit $C = vx_1x_2 \dots x_rv$ passing through both Q_1^v, Q_2^v such that every vertex x_i is locally connected for every $i \in \{2, \dots, r - 1\}$. By Lemma 2.3, v is locally connected in $cl(G)$. And this completes the proof of Claim 3.1. \square

Thus, every non-locally connected vertex of $cl(G)$ is contained in a 2-vertex cut of G .

Let $T = \{u, v\}$ be a 2-vertex cut separating the graph G into two components $Q_1(u, v)$ and $Q_2(u, v)$, let $G_i(u, v) = Q_i(u, v) \cup T$ for each $i = \{1, 2\}$. [That is, $G_1(u, v) \cup G_2(u, v) = G$ and $V(G_1(u, v)) \cap V(G_2(u, v)) = T$]. We say $G_i(u, v)$ is path-trivial for $i \in \{1, 2\}$ if $G_i(u, v)$ is either a chordless path with ends at v and u or a chordless circuit containing the edge vu .

Claim 3.2 At least one of $\{G_1(u, v), G_2(u, v)\}$ is path-trivial.

Proof Let $P_i(u, v)$ be a shortest path of $G_i(u, v)$ joining v and u , for $i = 1, 2$. Let $G_i^*(u, v) = G_i(u, v) \cup P_j(u, v)$, for every $\{i, j\} = \{1, 2\}$.

Prove by contradiction. Assume that $G_j(u, v) \neq P_j(u, v)$, for every $j \in \{1, 2\}$. Since G is a smallest counterexample, each $G_i^*(u, v)$ contains a Hamilton circuit $C_i(u, v)$. Note that the circuit $C_i(u, v)$ contains the non-trivial path $P_j(u, v)$ for every $\{i, j\} = \{1, 2\}$. Joining $C_1(u, v)$ and $C_2(u, v)$, we have a Hamilton circuit in G .

Thus, we may assume that $G_2(u, v) = P_2(u, v)$. That is, $G_2(u, v)$ is a chordless path or a chordless circuit containing the edge vu . \square

Now, for every 2-vertex cut $T = \{u, v\}$ of G , at least one of $\{G_1(u, v), G_2(u, v)\}$ is path-trivial (suppose $G_2(u, v)$). And furthermore, both v and u are non-locally connected in both G and $cl(G)$ due to Lemma 2.6.

Define \mathcal{T} be the set of all 2-vertex cuts of G .

(**) Choose $T = \{w, w'\} \in \mathcal{T}$ such that the path trivial part $|V(Q_2(w, w'))|$ is as large as possible.

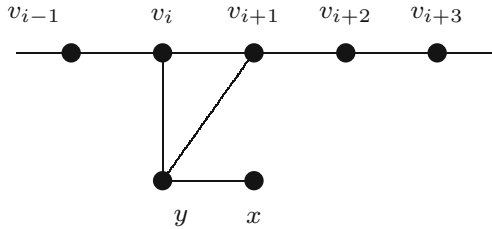
Note that every essential circuit passing through w (or w' , as well) must contain $G_2(w, w')$.

(***) Let C be a shortest essential circuit passing through w and w' ,

where $C = v_1 \dots v_r \dots v_s v_1$ with $v_1 = w, v_r = w', v_{r+1} \dots v_s = Q_2(w, w')$, and $v_r v_{r+1} \dots v_s v_1 = G_2(w, w')$. It is easy to see that $r \geq 2, s \geq r + 1$.

Define $Y_i = \{y \notin V(C) : distance_G(y, V(C)) = i\}$. By Claim 3.2, for each $i \geq 1, Y_i \subseteq Q_1(v_1, v_r)$.

Fig. 4 $N(y) \cap V(C) = \{v_i, v_{i+1}\}$



Claim 3.3 For each $y \in Y_1$,

- (i) if y is not locally connected, then $N(y) \cap V(C) = \{v_i, v_{i+1}\}$ for some $i \in \{1, \dots, r - 1\}$.
- (ii) if y is locally connected, then $\{v_i, v_{i+1}\} \subseteq N(y) \cap V(C) \subseteq \{v_i, v_{i+1}, v_{i+2}\}$ for some $i \in \{1, \dots, r - 1\}$.

Proof Since $G_2(v_1, v_r) = v_r \dots v_s v_1$ is path trivial, $N(y) \cap V(C) \subseteq \{v_1, \dots, v_r\}$. Choose $v_i \in N(y) \cap V(C)$ with i as small as possible.

Since C is a shortest essential circuit passing through v_1 and v_r , we have each vertex $v_j \notin N(y)$, where $i + 3 \leq j \leq r$, for otherwise, $v_1 \dots v_i y v_j \dots v_r \dots v_s v_1$ is shorter than C .

If $v_{i+1} \notin N(y)$, then $G[v_i, y, v_{i-1}, v_{i+1}]$ is a claw. Hence, both $v_i, v_{i+1} \in N(y)$.

If $v_{i+2} \in N(y)$ and y is not locally connected, then, by Lemma 2.2, C has a chord $v_i v_{i+2}$. This contradicts that C is chordless. □

Claim 3.4 $Y_2 \cup Y_3 \cup Y_4 \dots = \emptyset$

Proof We prove this result by contradiction. Let $x \in Y_2$ and $x y v_i$ be a shortest path joining x and $V(C)$ and choose v_i such that the subscript i is as small as possible. Note that $N(y) \cap V(C) \subseteq \{v_1, v_2, \dots, v_r\}$ since $\{v_{r+1}, \dots, v_s\} = V(Q_2(w, w'))$ (see Fig. 4).

By Claim 3.3, $\{v_i, v_{i+1}\} \subseteq N(y) \cap V(C) \subseteq \{v_i, v_{i+1}, v_{i+2}\}$ for some $i \in \{1, \dots, r - 1\}$. Furthermore, if $v_{i+2} \in N(y) \cap V(C)$, then $G[y, x, v_i, v_{i+2}]$ is a claw. Therefore, $N(y) \cap V(C) = \{v_i, v_{i+1}\}$. Hence, it is easy to see that induced subgraphs $N_{1,1,g_e(G)-4}$ and $N_{1,0,g_e(G)-3}$ are contained in the subgraph $G[x, y, V(C)]$ which contradicts the assumption. □

Claim 3.5 Every vertex in Y_1 is locally connected in G .

Proof Assume not. Choose $z \in Y_1$ and $v_i \in V(C)$ such that z is not locally connected in G and $v_i z \in E(G)$ and i is as small as possible. By Claim 3.3, $N(z) \cap V(C) = \{v_i, v_{i+1}\}$ and $1 \leq i \leq r - 1$. Here, assume that $\{v_i, v_{i+1}\} \subseteq Q_1^z$. By Lemma 2.2 and Claim 3.3, let $z' \in Q_2^z$ and $z' \notin V(C)$ (see Fig. 5).

By Claim 3.4, $z' \in Y_1$ and let $z' v_k \in E(G)$ where $v_k \in V(C)$ with k as large as possible. Since $g_e(G) \geq 6$, the length of the essential circuit $z v_{i+1} v_{i+2} \dots v_{k-1} v_k z' z$ is at least 6. Thus, we obtain another essential circuit $z z' v_k v_{k+1} \dots v_i z$ of $w = v_1$ that is of length shorter than C , a contradiction. □

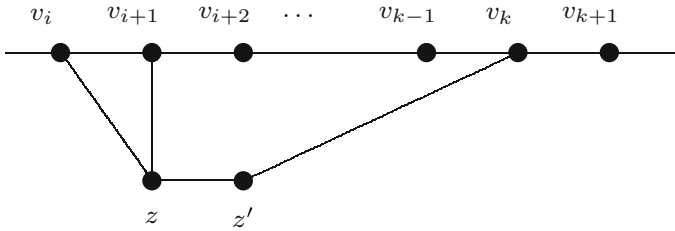


Fig. 5 Every vertex in Y_1 is locally connected in G

Claim 3.6 Furthermore, every vertex v of the component $Q_1(v_1, v_r)$ is locally connected in $cl(G)$.

Proof Prove by contradiction. Let v be a non-locally connected vertex in $cl(G)$. By Claim 3.5, $v \notin Y_1$. That is, $v = v_i \in V(C)$. Here, $1 < i < r$. Choose v_i such that i is as small as possible.

By Claim 3.1, v_i is contained in a 2-vertex cut $T' = \{v_i, x\}$.

Case 1. $x \in V(C)$.

We may assume that $x = v_h$ with h as small as possible. That is, by the choice of i , we have $i + 1 \leq h \leq r$. Let $Q_1(v_i, v_h)$ and $Q_2(v_i, v_h)$ be components of $G - \{v_i, v_h\}$. By Claim 3.2, let $Q_2(v_i, v_h)$ be path trivial. If $Q_2(v_i, v_h)$ contains $Q_2(v_1, v_r)$, then it contradicts (**). Since every vertex in the path trivial part $Q_2(v_i, v_h)$ is non-locally connected, by Claim 3.5, it is not in Y_1 . That is, $Q_2(v_i, v_h)$ is the segment $v_i \dots v_h$ of C and therefore, $i + 1 < h \leq r$.

By (**), let P^* be a shortest path of $G - Q_2(v_1, v_r) - Q_2(v_i, v_h)$ joining $\{v_1, \dots, v_i\}$ and $\{v_h, \dots, v_r\}$. By Claim 3.4, $P^* - V(C)$ has only two vertices z_1, z_2 where z_1 is adjacent to v_a with $1 \leq a \leq i$ while z_2 is adjacent to v_b with $h \leq b \leq r$. By (*) and Claim 2.2, the essential circuit $v_a \dots v_b z_2 z_1 v_a$ is of length at least 6. And by (***), $|\{v_a, \dots, v_b\}| = 4$.

Reroute the circuit C by replacing the segment $v_a \dots v_b$ with the path P^* , and apply Claim 3.5 to both vertices of $\{v_{a+1}, v_{b-1}\}$. This contradicts that each vertex of $Q_2(v_i, v_h) = v_{i+1} \dots v_{h-1}$ is non-locally connected in G .

Case 2. $x \notin V(C)$.

By Claim 3.4, $x \in Y_1$. Thus, $V(C) - v_i \subseteq Q_1(v_i, x)$. By Claim 3.5, x is locally connected in G which contradicts Lemma 2.6 that x must be non-locally connected in G as v_i is non-locally connected. □

So, every vertex of G , except for $V(G_2(v_1, v_r)) = \{v_r, \dots, v_s, v_1\}$, is locally connected and $Q_2(v_1, v_r)$ is a path attaching v_1, v_r . Then, in the closure $cl(G)$, the subgraph induced by $V(Q_1(v_1, v_r))$ is a complete graph, and the subgraph induced by $V(Q_2(v_1, v_r))$ remains as the path attaching v_1, v_r or a circuit containing the edge $v_1 v_r$. It is easy to see that $cl(G)$ has a Hamilton circuit and, by Theorem 2.1, so is G . It contradicts that G is a counterexample and, therefore, completes the proof of the Theorem 1.9.

References

1. Bedrossian, P.: Forbidden subgraph and minimum degree conditions for hamiltonicity. Ph.D. thesis, Memphis State University (1991)
2. Broersma, H.J., Kriesell, M., Ryjáček, Z.: On factors of 4-connected claw-free graphs. *J. Graph Theory* **37**, 125–136 (2001)
3. Broersma, H.J., Veldman, H.J.: Restrictions on induced subgraphs ensuring Hamiltonicity or pancyclicity of $K_{1,3}$ -free graphs. In: Bondendiek, R. (ed.) *Contemporary Methods in Graph Theory*, pp. 181–194. BI-Wiss-Verlag, Mannheim (1990)
4. Brousek, J., Faudree, R.J., Ryjáček, Z.: A note on hamiltonicity of generalized net-free graphs of large diameter. *Discrete Math.* **251**, 77–85 (2002)
5. Chiba S., Fujisawa, J.: Hamiltonicity of 3-connected generalized bull-free line graphs. [http://www.rs.kagu.tus.ac.jp/chiba/forbidden-subgraph\(B_%7Bs,t%7D\).pdf](http://www.rs.kagu.tus.ac.jp/chiba/forbidden-subgraph(B_%7Bs,t%7D).pdf)
6. Duffus, D., Gould, R.J., Jacobson, M.S.: *Forbidden Subgraphs and the Hamiltonian Theme, The Theory and Applications of Graphs*, Kalamazoo, Michigan, 1980. Wiley, New York (1981)
7. Faudree, R.J., Gould, R.J., Ryjáček, Z., Schiermejer, I.: Forbidden subgraphs and pancyclicity. *Congr. Numer.* **109**, 13–32 (1995)
8. Faudree, R.J., Gould, R.J.: Characterizing forbidden pairs for hamiltonian properties. *Discrete Math.* **173**, 45–60 (1997)
9. Fujiwasa, J.: Forbidden Subgraphs for Hamiltonicity of 3-connected claw-free graphs. *J. Graph Theory* **73**, 146–160 (2013)
10. Gould, R.J., Jacobson, M.S.: Forbidden subgraphs and hamiltonian properties of graphs. *Discrete Math.* **42**, 189–196 (1982)
11. Haray, F., Nash-Williams, C.S.J.A.: On Eulerian and Hamiltonian graphs and line graphs. *Can. Math. Bull.* **8**, 701–710 (1965)
12. Kaiser, T., Li, M., Ryjáček, Z., Xiong, L.: Hourglass and Hamilton cycle in 4-connected claw-free graphs. *J. Graph Theory* **48**, 267–276 (2005)
13. Lai, H.-J., Xiong, L., Yan, H., Yan, J.: Every 3-connected claw-free Z_8 -free graph is Hamiltonian. *J. Graph Theory* **64**, 1–11 (2010)
14. Matthews, H.M., Sumner, D.P.: hamiltonian results in $K_{1,3}$ -free graphs. *J. Graph Theory* **8**, 139–146 (1984)
15. Pfender, Florian: Hamiltonicity and forbidden subgraphs in 4-connected graphs. *J. Graph Theory* **49**, 262–272 (2005)
16. Ryjáček, Z.: On a closure concept in claw-free graphs. *J. Comb. Theory Ser. B* **70**, 217–224 (1997)