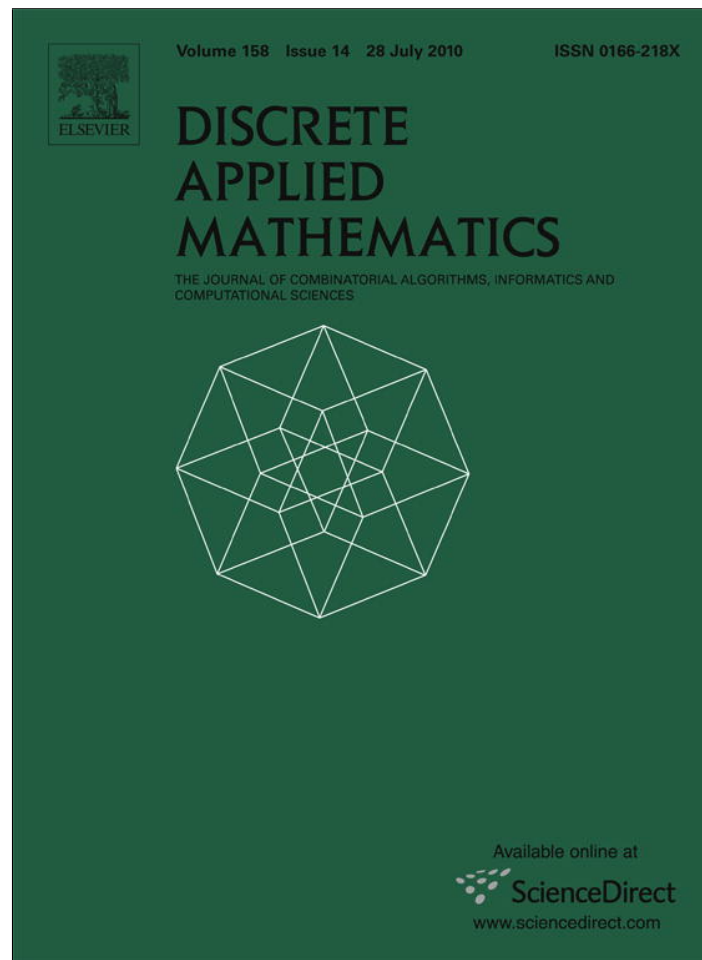


Provided for non-commercial research and education use.  
Not for reproduction, distribution or commercial use.



This article appeared in a journal published by Elsevier. The attached copy is furnished to the author for internal non-commercial research and education use, including for instruction at the authors institution and sharing with colleagues.

Other uses, including reproduction and distribution, or selling or licensing copies, or posting to personal, institutional or third party websites are prohibited.

In most cases authors are permitted to post their version of the article (e.g. in Word or Tex form) to their personal website or institutional repository. Authors requiring further information regarding Elsevier's archiving and manuscript policies are encouraged to visit:

<http://www.elsevier.com/copyright>



Contents lists available at ScienceDirect

## Discrete Applied Mathematics

journal homepage: [www.elsevier.com/locate/dam](http://www.elsevier.com/locate/dam)

## Balanced and 1-balanced graph constructions

Arthur M. Hobbs<sup>a</sup>, Lavanya Kannan<sup>a,\*</sup>, Hong-Jian Lai<sup>b</sup>, Hongyuan Lai<sup>c</sup>, Guoqing Weng<sup>b</sup><sup>a</sup> Texas A&M University, College Station, TX 77843-3368, United States<sup>b</sup> West Virginia University, Morgantown, WV 26506-6310, United States<sup>c</sup> Schoolcraft College, Livonia, MI 48152-2696, United States

## ARTICLE INFO

## Article history:

Received 31 July 2009

Received in revised form 9 April 2010

Accepted 9 May 2010

Available online 9 June 2010

## Keywords:

Balanced graphs

1-balanced graphs

Cartesian product of graphs

Web graphs

## ABSTRACT

There are several density functions for graphs which have found use in various applications. In this paper, we examine two of them, the first being given by  $b(G) = |E(G)|/|V(G)|$ , and the other being given by  $g(G) = |E(G)|/(|V(G)| - \omega(G))$ , where  $\omega(G)$  denotes the number of components of  $G$ . Graphs for which  $b(H) \leq b(G)$  for all subgraphs  $H$  of  $G$  are called *balanced graphs*, and graphs for which  $g(H) \leq g(G)$  for all subgraphs  $H$  of  $G$  are called *1-balanced graphs* (also sometimes called *strongly balanced* or *uniformly dense* in the literature). Although the functions  $b$  and  $g$  are very similar, they distinguish classes of graphs sufficiently differently that  $b(G)$  is useful in studying random graphs,  $g(G)$  has been useful in designing networks with reduced vulnerability to attack and in studying the World Wide Web, and a similar function is useful in the study of rigidity. First we give a new characterization of balanced graphs. Then we introduce a graph construction which generalizes the Cartesian product of graphs to produce what we call a *generalized Cartesian product*. We show that generalized Cartesian product derived from a tree and 1-balanced graphs are 1-balanced, and we use this to prove that the generalized Cartesian products derived from 1-balanced graphs are 1-balanced.

© 2010 Elsevier B.V. All rights reserved.

## 1. Introduction

We follow the notation of Diestel [3] for graphs, with the major exceptions that we use  $K_n$  for the complete graph on  $n$  vertices and we use  $b(G)$  for the function  $\epsilon(G) := \frac{|E(G)|}{|V(G)|}$ . Graphs considered in this paper are loopless, but multiple edges are allowed. If a graph has an edge, it is called *non-trivial*. In this paper we look at two density functions, both related to the average degree of a graph. The first of these is  $b(G) = \frac{|E(G)|}{|V(G)|}$  for a graph  $G$ . Graph  $G$  is said to be *balanced* if for all non-trivial subgraphs  $H$  of  $G$ ,

$$b(H) \leq b(G)$$

and *strictly balanced* if for all non-trivial proper subgraphs  $H$  of  $G$ ,

$$b(H) < b(G).$$

If  $G$  is connected, we also refer to a balanced graph as 0-balanced. Balanced graphs have been widely studied, particularly in the context of random graphs; for example, see [12,4,5,17,21].

The second density function we consider is  $g(G) = |E(G)|/\rho(G)$ , whose denominator  $\rho(G)$  is the *rank* of a graph  $G$  given by  $|V(G)| - \omega(G)$ , where  $\omega(G)$  is the number of components of  $G$ . (Note that  $\rho(G)$  is also the rank of the circuit matroid  $M(G)$

\* Corresponding address: Stowers Institute for Medical Research, Kansas City, MO-64114, United States. Tel.: +1 8169264496; fax: +1 8169264674.  
E-mail address: [lka@stowers.org](mailto:lka@stowers.org) (L. Kannan).

derived from the graph  $G$ ; see Oxley's book [15] for matroid terminology.) If  $X \subseteq E(G)$ , then the *rank*  $\rho(X)$  of  $X$  is the rank of the induced graph  $G[X]$ .

A graph  $G$  is *1-balanced* if, for every non-trivial subgraph  $H \subseteq G$ ,  $g(H) \leq g(G)$ . The 1-balanced graphs and matroids have been studied by many researchers; see [2,7,13,14,16,19,20], and the references listed in those papers. Other names for a 1-balanced graph include “molecular graph” [13,14], “strongly balanced graph” [12,19], and “uniformly dense” [10,11].

The *prism* on a graph  $G$  is the Cartesian product of  $G$  with  $K_2$ . It can also be seen as being formed by letting  $G'$  be a disjoint isomorphic copy of  $G$  and joining each vertex  $a$  of  $G$  to the vertex  $a'$  of  $G'$  corresponding to  $a$  under the isomorphism, thus forming a matching between the two copies of  $G$ . In [18], Piazza and Ringeisen generalized the prism on  $G$  by taking two disjoint copies  $G_1$  and  $G_2$  of  $G$  and a permutation  $\alpha$  of the vertices of  $G_2$ , and joining each vertex  $v_i$  of  $G_1$  to the vertex  $\alpha(v_i)$  of  $G_2$ . In [11], Hobbs et al. generalized the prism on  $G$  further by allowing  $G_1$  and  $G_2$  to be non-isomorphic but on the same numbers of vertices, and by replacing the matching joining them by a  $k$ -regular bipartite graph having as its two sides the vertex sets of  $G$  and  $G'$ . The “generalized prisms” motivate us to consider further generalizations of Cartesian products. In this paper, we present one such generalization, which contains both the Cartesian product and the generalized prisms as special cases. We also present in this paper characterizations for graphs whose generalized products are balanced, and for graphs whose generalized products are 1-balanced.

The construction of bigger 1-balanced graphs from smaller ones would be useful in the context of web-graphs, which have vertices representing web pages and edges corresponding to the links between pages. The structure of the web is often cited [1] as a bow tie, whose knot consists of a strongly connected component, called the *core*; and web-pages on the two sides of the knot consist respectively of those which link towards and away from the core. The core has been observed to be growing in its size over the years [9] and the cause for the growth is attributed to the increasing connectivity between existing web pages. Presences of *hubs* (vertices with high degrees) and *communities* (subgraphs which have more internal links than the external ones) dominate the web [6], which are also involved in the augmentation process of the core. 1-balanced graphs are described to be survivable under attacks on edges [10] and so it is of interest to construct 1-balanced graphs as the cores for the web-graphs. To be able to analyze the properties of the growing core, it would be of interest to design bigger networks from already existing smaller communities that may be modeled as 1-balanced graphs. Constructing bigger 1-balanced graphs from smaller ones would be useful in the context of realizing bigger survivable cores from existing communities.

In this paper, we are interested in constructing bigger 1-balanced graphs from already existing smaller 1-balanced subgraphs of equal density. Our main result is: if all the small 1-balanced graphs have the same number of edges and vertices, then the graphs in a class of generalized product of the 1-balanced graphs is 1-balanced. This generalizes our earlier result [11, Theorem 5] that Cartesian products of 1-balanced graphs are 1-balanced. The rest of the paper is organized as follows. In the next section, we give some preliminary results about 1-balanced graphs that will be used in the paper, and also give the definition of the generalized Cartesian graphs. In Section 3, we prove a new characterization of balanced graphs involving integer-valued functions on the vertices, and use it to prove that the generalized Cartesian product constructed from balanced graphs is balanced. In Section 4, we prove our main result, which makes use of the result on balanced generalized Cartesian products.

## 2. Preliminaries

### 2.1. Some results on 1-balanced graphs

We first recall some earlier results that are used in the paper. The following lemma is immediate for 1-balanced graphs.

**Lemma 1.** *A graph  $G$  is 1-balanced if and only if for all non-trivial **connected** subgraphs  $H$  of  $G$ , we have  $g(H) \leq g(G)$ .*

**Proof.** The necessity is clear. For sufficiency, suppose for all non-trivial, induced, connected subgraphs  $H$  of  $G$ ,  $g(H) \leq g(G)$ . Let  $H$  be a disconnected subgraph of  $G$ . Let  $H_i$ ,  $1 \leq i \leq \omega(H)$  be the components of  $G$ . Clearly, we may assume that  $H_i$  for  $1 \leq i \leq \omega(H)$  are non-trivial. By hypothesis,  $g(H_i) \leq g(G)$ , so  $|E(H_i)| \leq g(G)(|V(H_i)| - 1)$  for  $1 \leq i \leq \omega(H)$ . Hence

$$|E(H)| = \sum_{i=1}^{\omega(H)} |E(H_i)| \leq g(G) \sum_{i=1}^{\omega(H)} (|V(H_i)| - 1) = g(G)(|V(H)| - \omega(H)),$$

and so  $g(H) \leq g(G)$ .  $\square$

As a consequence of the above lemma, we can observe that for a connected graph  $G$ , in order to check if  $G$  is 1-balanced, it suffices to check if  $g(H) \leq g(G)$  for all connected subgraphs  $H$  of  $G$ . For the purposes of this paper, all graphs considered in the paper are connected. When we refer to Cartesian products, we refer to Cartesian products of connected graphs.

**Theorem 2** (Catlin et al. [2]). *Let  $G$  be a connected graph with  $g(G) = \frac{x}{y}$ , where  $x$  and  $y$  are natural numbers. Then,  $G$  is 1-balanced if and only if there is a family  $\mathcal{T}$  of  $x$  spanning trees in  $G$  such that each edge of  $G$  lies in exactly  $y$  trees of  $\mathcal{T}$ .*

The following are consequences of **Theorem 2**.

**Corollary 3.** *If a graph  $G$  is an edge-disjoint union of spanning 1-balanced subgraphs  $G_1, G_2, \dots, G_p$  for some integer  $p \geq 1$ , then  $G$  is 1-balanced.*

**Proof.** We show the result for  $p = 2$ . For  $p > 2$ , the result follows by induction on  $p$ . Since  $G_1$  and  $G_2$  are connected 1-balanced graphs on the same number of vertices, for  $x_1 = |E(G_1)|$ ,  $x_2 = |E(G_2)|$  and  $y = |V(G)| - 1$ ,  $g(G_1) = \frac{x_1}{y}$  and  $g(G_2) = \frac{x_2}{y}$ . Thus  $g(G) = \frac{x_1+x_2}{y}$ . For  $i = 1, 2$ , since  $G_i$  is 1-balanced,  $G_i$  has  $x_i$  spanning trees such that each edge in  $G_i$  is in exactly  $y$  of them. Thus  $G$  has  $x_1 + x_2$  spanning trees such that each edge in  $G$  is in exactly  $y$  of them.  $G$  is 1-balanced by **Theorem 2**.  $\square$

For a positive integer  $x$ , let  $G^x$  denote the graph obtained by replacing each edge of  $G$  by  $x$  parallel edges. The next corollary can be derived from **Corollary 3**.

**Corollary 4.** *Let  $x$  be a positive integer. A graph  $G$  is 1-balanced if and only if  $G^x$  is 1-balanced.*

### 2.2. Generalized Cartesian products

Throughout this section, let  $e, n, \ell$  and  $m$  be integers with  $e \geq n - 1 \geq 1$  and  $\ell \geq m - 1 \geq 1$ , let  $L$  be a graph with  $\ell$  edges and  $m$  vertices, and let the vertices of  $L$  be labeled  $v_1, v_2, \dots, v_m$ . Label the edges of  $L$  as  $e_1, e_2, \dots, e_\ell$ . Let  $G_1, G_2, \dots, G_m$  be vertex-disjoint graphs, each having  $n$  vertices and  $e$  edges. Let  $k$  be a positive integer. Let  $B_1, B_2, \dots, B_\ell$  be  $k$ -regular bipartite graphs (may be disconnected) such that, if edge  $e_i$  of  $L$  joins vertices  $v_r$  and  $v_s$ , then the two sides of  $B_i$  are the vertex sets of  $G_r$  and  $G_s$ . Let  $A_k = A_k(G_1, \dots, G_m; L) = \left( \bigcup_{i=1}^m G_i \right) \cup \left( \bigcup_{i=1}^{\ell} B_i \right)$ . When the value of  $k$  is already known, we may use  $A = A(G_1, \dots, G_m; L)$ , with the subscript  $k$  omitted. Then  $A_k$  or  $A$  is called a *generalized Cartesian product*. Note that the definition of  $A_k$  is ambiguous, since there are many possible  $k$ -regular bipartite graphs  $B_i$ . We allow this ambiguity because the choices of the  $B_i$  make no difference to our results. Also note that if  $G$  and  $L$  are graphs, then the Cartesian product  $G \times L$  is a generalized Cartesian product with  $G_i = G$  for  $i = 1, 2, \dots, m$  and  $k = 1$ .

Let  $H$  be a subgraph of  $A$ , and suppose  $H$  includes one or more vertices of  $G_{i_1}, \dots, G_{i_\ell}$  and no others of the  $G_i$ . Let  $L'$  be the subgraph of  $L$  generated by the vertices  $v_{i_1}, \dots, v_{i_\ell}$ . Then we say that  $L'$  is *induced by  $H$* .

### 3. Characterizations of balanced graphs and balanced generalized Cartesian products

In this section, we first provide a new characterization of balanced graphs which is used to construct bigger balanced graphs from smaller ones, which in turn is used in the last section to construct bigger 1-balanced graphs from smaller 1-balanced graphs. The characterization is also used to show that the Cartesian product of balanced graphs is balanced.

The next theorem is our new characterization of balanced graphs. The characterization involves arbitrary non-negative integer vertex weights.

**Theorem 5.** *Let  $L$  be a graph on  $m$  vertices  $V = \{v_1, \dots, v_m\}$ . Let  $\alpha$  be any non-negative integer-valued function on the vertex set  $V$ . Let*

$$N_\alpha := \sum_{v_i v_j \in E(L)} \left[ \min(\alpha(v_i), \alpha(v_j)) - \frac{1}{m} \sum_{r=1}^m \alpha(v_r) \right].$$

*Then  $L$  is balanced if and only if  $N_\alpha \leq 0$  for all  $\alpha$ , and  $L$  is strictly balanced if and only if  $N_\alpha < 0$  for all non-constant  $\alpha$ .*

**Proof (Sufficiency of  $L$  Balanced).** For a contradiction, suppose  $L$  is balanced while there is a non-negative, integer-valued function  $\alpha$  on  $V(L)$  with  $N_\alpha > 0$ . Choose  $\alpha_0$  such that  $N_{\alpha_0} > 0$  and  $s = \max_{1 \leq i \leq m} \alpha_0(v_i)$  is as small as possible. If  $\alpha_0$  were constant on  $\{v_1, \dots, v_m\}$ , then  $N_{\alpha_0} = 0$ . Hence, there is a  $j \in \{1, 2, \dots, m\}$  such that  $\alpha_0(v_j) < s$ . Then  $s \geq 1$  since  $\alpha_0(v_i) \geq 0$ .

Let  $S := \{v_i : \alpha_0(v_i) = s\}$ . By the definition of  $s$  and  $j$ ,  $S \neq \emptyset, V$ . Consider the function  $\alpha'_0$  defined by  $\alpha'_0(v_i) = \alpha_0(v_i)$  if  $v_i \notin S$  and  $\alpha_0(v_i) - 1$  if  $v_i \in S$ . Thus  $\max_{1 \leq i \leq m} \alpha'_0(v_i) < s$ .

We claim that  $N_{\alpha'_0} \geq N_{\alpha_0}$ .

Let  $L' := L[S]$ , and denote  $m' := |V(L')| = |S|$  and  $\ell' := |E(L')|$ . Then

$$\begin{aligned} \frac{1}{m} \sum_{r=1}^m \alpha'_0(v_r) &= \frac{1}{m} \left[ \sum_{r:v_r \notin S} \alpha_0(v_r) + \sum_{r:v_r \in S} (\alpha_0(v_r) - 1) \right] \\ &= \frac{1}{m} \left[ \sum_{r:v_r \notin S} \alpha_0(v_r) + \sum_{r:v_r \in S} \alpha_0(v_r) - m' \right] \\ &= \frac{1}{m} \sum_{r=1}^m \alpha_0(v_r) - \frac{m'}{m}. \end{aligned}$$

Suppose  $v_i v_j \in E(L)$ . Then  $\min(\alpha'_0(v_i), \alpha'_0(v_j)) = \min(\alpha_0(v_i), \alpha_0(v_j)) - 1$ . Therefore, in this case we have

$$\min(\alpha'_0(v_i), \alpha'_0(v_j)) - \frac{1}{m} \sum_{r=1}^m \alpha'_0(v_r) = \min(\alpha_0(v_i), \alpha_0(v_j)) - 1 - \frac{1}{m} \sum_{r=1}^m \alpha_0(v_r) + \frac{m'}{m}.$$

If  $v_i v_j \notin E(L)$ , then  $\min(\alpha'_0(v_i), \alpha'_0(v_j)) = \min(\alpha_0(v_i), \alpha_0(v_j))$ . This is true even if, for example,  $v_i \in S$  and  $v_j \notin S$ , for then  $\alpha'_0(v_i) = s - 1$  and  $\alpha'_0(v_j) = \alpha_0(v_j) \leq s - 1$ , and so  $\min(\alpha'_0(v_i), \alpha'_0(v_j)) = \min(s - 1, \alpha_0(v_j)) = \alpha_0(v_j) = \min(\alpha_0(v_i), \alpha_0(v_j))$ . Thus we have

$$\min(\alpha'_0(v_i), \alpha'_0(v_j)) - \frac{1}{m} \sum_{r=1}^m \alpha'_0(v_r) = \min(\alpha_0(v_i), \alpha_0(v_j)) - \frac{1}{m} \sum_{r=1}^m \alpha_0(v_r) + \frac{m'}{m}.$$

Therefore,

$$N_{\alpha'_0} - N_{\alpha_0} = \ell' \left( -1 + \frac{m'}{m} \right) + (\ell - \ell') \frac{m'}{m} = -\ell' + \frac{\ell m'}{m} = m' \left( -\frac{\ell'}{m'} + \frac{\ell}{m} \right) \geq 0$$

since  $\frac{\ell'}{m'} = b(L') \leq b(L) = \frac{\ell}{m}$  either because  $L$  is balanced or because  $\ell' = 0$ . Hence the claim.

But  $N_{\alpha'_0} \geq N_{\alpha_0} > 0$  is a contradiction to the minimality of  $s$  by the definition of  $N_{\alpha'_0}$ . The contradiction proves sufficiency.

**(Necessity of  $L$  balanced)** Suppose  $N_{\alpha} \leq 0$  for all labelings  $\alpha$ . Let  $L'$  be any non-trivial vertex-induced subgraph of  $L$ , and suppose  $L'$  has  $m'$  vertices and  $\ell'$  edges. Define  $\alpha$  on  $V(L)$  by letting  $\alpha(v) = 1$  if  $v \in V(L')$  and 0 if  $v \notin V(L')$ . Then

$$\frac{1}{m} \sum_{r=1}^m \alpha(v_r) = \frac{m'}{m},$$

and

$$\begin{aligned} 0 &\geq N_{\alpha} \\ &= \sum_{v_i v_j \in E(L')} \left( 1 - \frac{m'}{m} \right) + \sum_{v_i v_j \notin E(L')} \left( -\frac{m'}{m} \right) \\ &= \ell' - \frac{m' \ell'}{m} - \frac{m' \ell}{m} + \frac{m' \ell'}{m} \\ &= \ell' - \frac{m' \ell}{m} \\ &= m' \left( \frac{\ell'}{m'} - \frac{\ell}{m} \right). \end{aligned}$$

Hence we have  $\frac{\ell'}{m'} \leq \frac{\ell}{m}$  (i.e.,  $b(L') \leq b(L)$ ), so  $L$  is balanced.

The proof for strictly balanced graphs is similar.  $\square$

Next, we prove that Cartesian products of balanced graphs are balanced. In fact, we will prove an extension of the result. We present a construction of bigger balanced graphs from smaller ones by joining some additional edges, namely, the following result for generalized Cartesian product defined in Section 2.

**Theorem 6.** Let  $L$  be a graph on  $m$  vertices and  $\ell$  edges. Let  $k$  be any positive integer and let  $G_1, \dots, G_m$  be balanced graphs, each on  $n$  vertices and  $e$  edges. Then  $A = A_k(G_1, \dots, G_m; L)$  is balanced if and only if  $L$  is balanced.

**Proof.**

$$b(A) = \frac{nk\ell + me}{mn} = \frac{k\ell}{m} + \frac{e}{n}. \tag{1}$$

Note that for  $i = 1, \dots, m$ ,

$$b(G_i) < b(A). \tag{2}$$

**(Necessity)** Suppose  $A$  is balanced. Let  $V(L) = \{v_1, v_2, \dots, v_m\}$ . Let  $L'$  be any subgraph of  $L$ , and suppose  $L'$  has  $\ell'$  edges and  $m'$  vertices. Form  $A'$  on  $L'$  as  $A$  is formed on  $L$ . Then,

$$b(A') = \frac{nk\ell' + m'e}{m'n} = \frac{k\ell'}{m'} + \frac{e}{n}. \tag{3}$$

Since  $A$  is balanced, we have  $b(A') \leq b(A)$ , and by (1) and (3), we have

$$\frac{k\ell'}{m'} \leq \frac{k\ell}{m}. \tag{4}$$

Thus

$$\frac{\ell'}{m'} \leq \frac{\ell}{m}. \tag{5}$$

Therefore  $L$  is balanced.

**(Sufficiency)** Suppose  $L$  is balanced. Let  $H$  be a subgraph of  $A$ . If  $H$  is a subgraph of a  $G_j$  for some  $j = 1, \dots, m$ , then since  $G_j$  is balanced, we have  $b(H) \leq b(G_j)$  and by (2), we have  $b(G_j) < b(L)$ ; thus  $b(H) < b(L)$ . Otherwise, let  $H_i = H \cap G_i$  and  $n_i = |V(H_i)|$  for  $i = 1, \dots, m$ . Without loss of generality, we may suppose that there is an integer  $m' > 0$  such that  $1 \leq n_1 \leq n_2 \leq \dots \leq n_{m'}$  and  $n_i = 0$  for  $i > m'$ . Let  $L'$  be the subgraph of  $L$  induced by  $H$ , and note that  $L' = L$  is possible. For each  $i \in \{1, 2, \dots, m'\}$ , let  $e_i = |E(H_i)|$ , and  $e' = |E(H) \cap E(\bigcup_{i=1}^{m'} B_i)|$ . Notice that

$$e' \leq k \sum_{v_i v_j \in E(L')} \min(n_i, n_j). \tag{6}$$

Since  $L$  is balanced, using  $\alpha(v_i) = n_i$  for  $i \in \{1, 2, \dots, m\}$  in Theorem 5 and using  $n_i = 0$  for  $i > m'$ , we have

$$\sum_{v_i v_j \in E(L')} \min(n_i, n_j) = \sum_{v_i v_j \in E(L')} \min(n_i, n_j) \leq \frac{l}{m} \sum_{i=1}^m n_i = \frac{l}{m} \sum_{i=1}^{m'} n_i. \tag{7}$$

By (6) and (7), we get

$$e' \leq \frac{kl}{m} \sum_{i=1}^{m'} n_i. \tag{8}$$

Thus,

$$b(H) = \frac{e' + \sum_{i=1}^{m'} e_i}{\sum_{i=1}^{m'} n_i} \tag{9}$$

$$\leq \frac{\frac{kl}{m} \sum_{i=1}^{m'} n_i + \sum_{i=1}^{m'} e_i}{\sum_{i=1}^{m'} n_i} \tag{10}$$

$$= \frac{kl}{m} + \frac{\sum_{i=1}^{m'} e_i}{\sum_{i=1}^{m'} n_i}. \tag{11}$$

By [8, Theorem 1, page 14], we have  $\frac{\sum_{i=1}^{m'} e_i}{\sum_{i=1}^{m'} n_i} \leq \max_{1 \leq i \leq m'} \frac{e_i}{n_i} \leq \frac{e}{n}$  since  $G_i$  is balanced for every  $i$ . Therefore,  $b(H) \leq \frac{kl}{m} + \frac{e}{n} = g(A)$  and thus  $A$  is balanced.  $\square$

**Corollary 7.** *The Cartesian product of balanced graphs is balanced.*

**Proof.** Let  $G$  and  $L$  be two balanced graphs. Then  $G \times L = A_1(G, G, \dots, G; L)$  with suitable choices of the bipartite graphs  $B_{ij}$ . By the above theorem,  $G \times L$  is balanced.  $\square$

#### 4. 1-balanced generalized Cartesian products

The method of generalized Cartesian products defined in Section 1 can be used to construct bigger 1-balanced graphs from smaller ones. In this section, we prove that 1-balanced generalized Cartesian products can be formed from 1-balanced graphs.

In this section we prove that  $A$  is 1-balanced if  $G_1, \dots, G_m$  and  $L$  are 1-balanced and  $k$  is a fixed integer such that

$$\frac{m-1}{\ell} \binom{t}{n} \leq k \leq \frac{m-1}{\ell} (mt). \tag{12}$$

The reason why we need the above bounds for  $k$  is explained in the next paragraph.

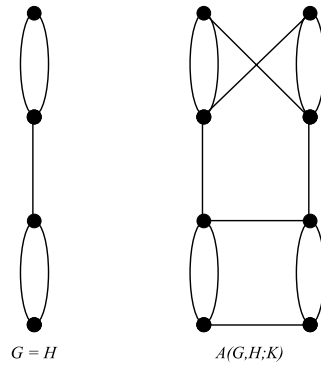


Fig. 1.  $A_1(G, H; K_2)$ : Example of a generalized Cartesian product that is 1-balanced, but neither  $G$  nor  $H$  is 1-balanced.

Let  $t = g(G_i) = \frac{e}{n-1}$  for all  $i \in \{1, 2, \dots, m\}$ . Unlike balanced generalized Cartesian products, the value of the positive integer  $k$  in a 1-balanced generalized Cartesian product has a non-trivial lower bound, as the following Lemma shows.

**Lemma 8.** *If  $A$  is 1-balanced, then*

$$k \geq \frac{m-1}{\ell} \binom{t}{n} = \frac{g(G_i)}{g(L)n}.$$

**Proof.** For each  $i$ , we have  $|E(B_i)| = 2nk/2 = nk$ . Since each  $G_i$  is connected and  $L$  is connected,  $A$  is connected. Hence

$$g(A) = \frac{nk\ell + m e}{mn - 1}.$$

Since  $A$  is 1-balanced and  $G_i$  is a subgraph of  $A$  for each  $i$ , we have

$$g(A) = \frac{nk\ell + m e}{mn - 1} \geq \frac{e}{n - 1} = g(G_i).$$

Solving for  $k$ , we get

$$k \geq \frac{m-1}{\ell} \binom{t}{n}. \quad \square$$

The need for an upper bound for  $k$  such as this for  $k$  is illustrated by the graph  $A = A_3(K_2, K_2; K_2)$ . Here,  $L = K_2$ ,  $t = 1$  and  $m = 2$ . We have  $\frac{m-1}{\ell} (mt) = 2 < 3$ . If  $H$  denotes the subgraph on 2 vertices and 3 parallel edges, then  $g(H) = 3$ . But,  $g(A) = \frac{2(3+1)}{3} = \frac{8}{3} < 3 = g(H)$ . Therefore  $A$  is not 1-balanced. Thus even the usual Cartesian product is not necessarily 1-balanced when  $k > \frac{m-1}{\ell} (mt)$ , even if  $G_1, \dots, G_m$  and  $L$  are 1-balanced.

That a generalized Cartesian product  $A = A_k(G_1, \dots, G_m; L)$  is 1-balanced does not imply that any of  $G_1, \dots, G_m$  or  $L$  is 1-balanced. The graph in Fig. 1 is an example of a generalized Cartesian product  $A_k(G, H; K_2)$  that is 1-balanced, but neither  $G$  nor  $H$  is 1-balanced. It is easy to see that  $A_1(G, H; K_2)$  is the union of 2 edge-disjoint spanning trees. Thus  $A$  is 1-balanced, by Theorem 2. Also, note that  $K_2$  is a subgraph of  $G$  and  $g(K_2) = 2$ , but  $g(G) = \frac{5}{3} < 2$ . Thus,  $G$  is not 1-balanced. Similarly,  $H$  is not 1-balanced.

However, we have this result:

**Theorem 9.** *If  $A$  is 1-balanced, then  $L$  is strictly balanced.*

**Proof.** Let  $V(L) = \{v_1, v_2, \dots, v_m\}$ . Let  $L'$  be any proper connected subgraph of  $L$ , and suppose  $L'$  has  $\ell'$  edges and  $m'$  vertices. Form  $A'$  on  $L'$  as  $A$  is formed on  $L$ . Then  $g(A') = \frac{nk\ell' + m'e}{m'n - 1}$ . Since  $A$  is 1-balanced, we have

$$\frac{nk\ell' + m'e}{m'n - 1} = g(A') \leq g(A) = \frac{nk\ell + m e}{mn - 1}.$$

Cross-multiplying and simplifying,

$$mn^2k\ell' + mm'n e - nk\ell' - m'e \leq m'n^2k\ell + mm'n e - nk\ell - m e,$$

or

$$\begin{aligned} mn^2k\ell' - nk\ell' - m'e &\leq m'n^2k\ell - nk\ell - m e \\ &< m'n^2k\ell - nk\ell' - m'e \end{aligned}$$

since  $\ell > \ell'$  and  $m > m'$ . Hence,

$$mn^2k\ell' - nk\ell' - m'e < m'n^2k\ell - nk\ell' - m'e,$$

which simplifies to  $m\ell' < m'\ell$  since  $n^2k > 0$ . Thus we have  $\frac{\ell'}{m'} < \frac{\ell}{m}$  as required.  $\square$

The converse of this theorem is false. Let  $L$  be the graph formed by the vertices  $\{a, b, c, d\}$  and edges  $(a, b)$ ,  $(b, c)$ ,  $(a, c)$  and  $(c, d)$ . Then  $g(L[\{a, b, c\}]) = \frac{3}{2} > 2 = g(L)$ . Thus  $L$  is not 1-balanced, but it can be easily verified that  $L$  is strictly balanced. Now, consider the Cartesian product of  $K_2$  and  $L$ ,  $A = A_1(K_2, K_2, K_2, K_2; L)$ . The Cartesian product of  $K_2$  and  $H := G[\{a, b, c\}]$  is a subgraph of  $A$ , and  $g(K_2 \times H) = \frac{9}{5} > \frac{12}{7} = g(A)$ . Thus  $A$  is not 1-balanced.

Throughout the rest of the paper, for any graph  $X$ , we refer to  $\gamma(X)$  as

$$\gamma(X) := \max_{X' \subseteq X} g(X'),$$

where the maximum is taken over all non-trivial subgraphs  $X'$  of  $X$ . We also call a non-trivial subgraph  $X'$  of  $X$  with  $g(X') = \gamma(X)$ , as a  $\gamma$ -achieving subgraph of  $X$ .

From now on, we assume that  $G_1, \dots, G_m$  are connected 1-balanced graphs. We first show that  $A$  is 1-balanced if  $k$  is as specified in (12) and  $L$  is a tree. Our plan of proof is to choose a  $\gamma$ -achieving, connected (in view of Lemma 1) subgraph  $H$  of  $A$ . We move to the subtree  $L'$  of  $L$  induced by  $H$  and prove  $g(H) \leq g(A')$  in that case. (It is here that we use the new characterization of balanced graphs, namely Theorem 5.) Using  $g(A') \leq g(A)$ , as shown in the next lemma, we conclude that  $g(H) \leq g(A)$ . Thus  $g(A) = \gamma(A)$  and  $A$  is 1-balanced.

We start with some lemmas. Let  $L$  be any 1-balanced graph, and let  $L'$  be a connected induced subgraph of  $L$ . Letting  $A'$  be constructed from  $L'$  as  $A$  is constructed from  $L$ , we first look at the relationship between  $g(A)$  and  $g(A')$  (Lemma 10) and between  $g(A)$  and  $g(G_i)$  (Lemma 11).

**Lemma 10.** Let  $t = \frac{e}{n-1} = g(G_i)$  for  $i \in \{1, 2, \dots, m\}$ , and let  $k \geq \frac{t}{g(L)n}$ . Let  $L'$  be a connected induced subgraph of  $L$ . Form  $A'$  from  $L'$  in the same way  $A$  is formed from  $L$ . If  $L$  is 1-balanced, then  $g(A') \leq g(A)$ .

**Proof.**

$$\begin{aligned} g(A) - g(A') &= \frac{nk\ell + me}{mn - 1} - \frac{nk\ell' + m'e}{m'n - 1} \\ &= \frac{nk\ell(m'n - 1) + mm'e - me - nk\ell'(mn - 1) - mm'e + m'e}{(mn - 1)(m'n - 1)} \\ &= \frac{nk\ell(m'n - 1) - me - nk\ell'(mn - 1) + m'e}{(mn - 1)(m'n - 1)}. \end{aligned}$$

Since  $\ell = g(L)(m - 1)$  and  $\ell' \leq g(L)(m' - 1)$ , we have

$$\begin{aligned} g(A) - g(A') &\geq \frac{g(L)nk(m - 1)(m'n - 1) - me - g(L)nk(m' - 1)(mn - 1) + m'e}{(mn - 1)(m'n - 1)} \\ &= \frac{g(L)nk[mm'n - m'n - m + 1 - mm'n + mn + m' - 1] - (m - m')e}{(mn - 1)(m'n - 1)} \\ &= \frac{g(L)nk[-m'n - m + mn + m'] - (m - m')e}{(mn - 1)(m'n - 1)} \\ &= \frac{g(L)nk[(m - m')(n - 1)] - (m - m')e}{(mn - 1)(m'n - 1)} \\ &= (m - m') \frac{g(L)nk(n - 1) - e}{(mn - 1)(m'n - 1)} \\ &= (m - m')(n - 1) \frac{g(L)nk - g(G_i)}{(mn - 1)(m'n - 1)} \\ &\geq 0 \end{aligned}$$

since  $k \geq \frac{g(G_i)}{g(L)n}$ .  $\square$

**Lemma 11.** With  $k \geq \frac{m-1}{\ell} \left(\frac{t}{n}\right)$ , we have  $g(G_i) \leq g(A)$ .

**Proof.** This was noted at the end of the proof of Lemma 8.  $\square$

From now on, we assume that  $k$  satisfies (12).

**Theorem 12.** Let  $L$  be a tree. Then  $A$  is 1-balanced.



**Proof.** If  $n = 1$ ,  $A = L$  and since  $L$  is 1-balanced,  $A$  is 1-balanced. We may assume that  $n > 1$ .

Suppose, for a contradiction, that  $A$  is not 1-balanced. Then by Lemma 1, there is an induced connected subgraph  $H$  of  $A$  such that  $g(H) = \gamma(A) > g(A)$ . Let  $H_i = H \cap G_i$  and  $n_i = |V(H_i)|$ . Without loss of generality, we may suppose there is an integer  $m' > 0$  such that  $1 \leq n_1 \leq n_2 \leq \dots \leq n_{m'}$  and  $n_i = 0$  for  $i > m'$ . Let  $L'$  be the subgraph of  $L$  induced by  $H$ , and note that  $L' = L$  is possible.  $L'$  is the same subgraph of  $L$  which is induced by  $\{v_1, \dots, v_{m'}\}$ . For each  $i \in \{1, 2, \dots, m'\}$ , let  $e_i = |E(H_i)|$ ,  $\omega_i = \omega(H_i)$ , and  $e' = |E(H) \cap E(\bigcup_{i=1}^{m'} B_i)|$ . Notice that

$$e' \leq k \sum_{v_i v_j \in E(L')} \min(n_i, n_j). \tag{13}$$

Since  $L$  is a tree and  $H$  is connected,  $L'$  is a tree.  $g(L) = 1$ . So,

$$\frac{t}{n} \leq k \leq mt. \tag{14}$$

Recall that  $g(A') \leq g(A)$  by Lemma 10. Thus

$$g(H) > g(A) \geq g(A'), \tag{15}$$

so  $A'$  is also not 1-balanced.

We consider two cases:

Case 1:  $\frac{t}{n} \leq k \leq m't$ .

First we show

$$\frac{nk\ell' - (m' - 1)t}{m'n - 1} < \frac{e' - (m' - 1)t}{\sum_{i=1}^{m'} n_i - 1}. \tag{16}$$

Since  $k \geq \frac{t}{n}$ ,  $g(A) \geq g(G_i)$  for each  $i$  by Lemma 11,  $H \not\subseteq G_i$  for any  $i$ , so  $m' > 1$ .

Recalling that  $t = g(G_i) = \frac{e}{n-1}$ ,

$$\begin{aligned} g(A') &= \frac{nk\ell' + m'e}{m'n - 1} \\ &= \frac{nk\ell' + m' \frac{e}{n-1} (n - 1)}{m'n - 1} \\ &= \frac{tm'(n - 1) + nk\ell'}{m'n - 1} \\ &= \frac{m'nt - t + t - m't + nk\ell'}{m'n - 1} \\ &= t + \frac{nk\ell' - (m' - 1)t}{m'n - 1}. \end{aligned} \tag{17}$$

Also,

$$g(H) = \frac{\sum_{i=1}^{m'} e_i + e'}{\sum_{i=1}^{m'} n_i - 1}.$$

But, with  $i \leq m'$ ,  $n_i \geq 1$ . Thus, if  $e_i \neq 0$ , then

$$e_i = \frac{e_i}{n_i - \omega_i} (n_i - \omega_i) \leq g(G_i)(n_i - \omega_i) \leq t(n_i - 1).$$

On the other hand, if  $e_i = 0$ , then

$$e_i = 0 \leq t(n_i - 1).$$

Thus, from the definitions of the symbols,

$$g(H) = \frac{\sum_{i=1}^{m'} e_i + e'}{\sum_{i=1}^{m'} n_i - 1}$$

$$\begin{aligned}
 &\leq \frac{t \sum_{i=1}^{m'} (n_i - 1) + e'}{\sum_{i=1}^{m'} n_i - 1} \\
 &= \frac{t \left( \sum_{i=1}^{m'} n_i - 1 \right) + t + e' - \sum_{i=1}^{m'} t}{\sum_{i=1}^{m'} n_i - 1} \\
 &= t + \frac{e' - (m' - 1)t}{\sum_{i=1}^{m'} n_i - 1}.
 \end{aligned} \tag{18}$$

Since  $g(A') < g(H)$ , (16) follows from (17) and (18).  
 Next we show that

$$\sum_{v_i v_j \in E(L')} \left[ \min(n_i, n_j) - \frac{1}{m'} \sum_{r=1}^{m'} n_r \right] > 0 \tag{19}$$

follows from (16), thus leading to a contradiction. But

$$\frac{nk\ell' - (m' - 1)t}{m'n - 1} = \frac{\frac{k\ell'}{m'} - (m' - 1)t}{m'n - 1} + \frac{k\ell'}{m'}.$$

Replacing the left-hand side of (16) with this, moving  $\frac{k\ell'}{m'}$  to the other side, and using (13),

$$\begin{aligned}
 \frac{\frac{k\ell'}{m'} - (m' - 1)t}{m'n - 1} &< \frac{-\frac{k\ell'}{m'} \sum_{i=1}^{m'} n_i + \frac{k\ell'}{m'} + k \sum_{v_i v_j \in E(L')} \min(n_i, n_j) - (m' - 1)t}{\sum_{i=1}^{m'} n_i - 1} \\
 &= \frac{\frac{k\ell'}{m'} + k \left( \sum_{v_i v_j \in E(L')} \left[ \min(n_i, n_j) - \frac{1}{m'} \sum_{i=1}^{m'} n_i \right] \right) - (m' - 1)t}{\sum_{i=1}^{m'} n_i - 1}.
 \end{aligned}$$

Multiplying through by the denominators and canceling like terms, we get

$$\frac{k\ell'}{m'} \sum_{i=1}^{m'} n_i - (m' - 1)t \sum_{i=1}^{m'} n_i < \frac{k\ell'}{m'} (m'n) + k(m'n - 1) \left( \sum_{v_i v_j \in E(L')} \left[ \min(n_i, n_j) - \frac{1}{m'} \sum_{i=1}^{m'} n_i \right] \right) - m'n(m' - 1)t.$$

Thus

$$\frac{k\ell'}{m'} \sum_{i=1}^{m'} n_i - \frac{k\ell'}{m'} (m'n) + m'n(m' - 1)t - (m' - 1)t \sum_{i=1}^{m'} n_i < k(m'n - 1) \left( \sum_{v_i v_j \in E(L')} \left[ \min(n_i, n_j) - \frac{1}{m'} \sum_{i=1}^{m'} n_i \right] \right).$$

Combining the two terms containing  $(m' - 1)t$  and then the first two terms of the previous inequality, we get

$$(m' - 1)t \sum_{i=1}^{m'} (n - n_i) - \frac{k\ell'}{m'} \left( m'n - \sum_{i=1}^{m'} n_i \right) < k(m'n - 1) \left( \sum_{v_i v_j \in E(L')} \left[ \min(n_i, n_j) - \frac{1}{m'} \sum_{i=1}^{m'} n_i \right] \right).$$

Combining the terms on the left hand side gives us

$$\left( (m' - 1)t - \frac{k\ell'}{m'} \right) \sum_{i=1}^{m'} (n - n_i) < k(m'n - 1) \left( \sum_{v_i v_j \in E(L')} \left[ \min(n_i, n_j) - \frac{1}{m'} \sum_{i=1}^{m'} n_i \right] \right). \tag{20}$$

But  $\sum_{i=1}^{m'} (n - n_i) \geq 0$  since  $n_i \leq n$  for all  $i$ . Moreover, since  $\ell' = m' - 1$ ,  $m' \geq 2$  and  $k \leq m't$ ,

$$(m' - 1)t - \frac{k\ell'}{m'} = (m' - 1) \left[ t - \frac{k}{m'} \right] \geq 0.$$

Thus the left hand side of (20) is non-negative. Since  $k(m'n - 1)$  is positive, the rest of the right hand side must be positive. Hence the inequality (19). But  $L'$  is a tree, and so it is 1-balanced and thus balanced. By Theorem 5, the inequality we have just reached is impossible. Thus  $A'$  is 1-balanced, so the proposed subgraph  $H$  cannot exist.

Case 2:  $m't \leq k \leq mt$ .

For this case, we show that  $g(A) < g(H)$  and  $k \geq m't$  together imply that  $k > mt$  which is a contradiction.

Using the similar computations we used in (17), we obtain

$$\begin{aligned}
 g(A) &= \frac{nk\ell + m'e}{mn - 1} \\
 &= \frac{nk\ell + m\frac{e}{n-1}(n-1)}{mn - 1} \\
 &= \frac{tm(n-1) + nk\ell}{mn - 1} \\
 &= \frac{mnt - t + t - mt + nk\ell}{mn - 1} \\
 &= t + \frac{nk\ell - (m-1)t}{mn - 1}.
 \end{aligned} \tag{21}$$

From (15), we have  $g(A) < g(H)$ . Thus by (18) and (21),

$$\frac{nk\ell - (m-1)t}{mn - 1} < \frac{e' - (m' - 1)t}{\sum_{i=1}^{m'} n_i - 1}. \tag{22}$$

Now, we will get a bound for  $e'$ . By (13), we have

$$e' \leq k \sum_{v_i v_j \in E(L')} \min(n_i, n_j).$$

By Theorem 5, since  $L'$  is a balanced graph,

$$\sum_{v_i v_j \in E(L')} \min(n_i, n_j) \leq \frac{\ell'}{m'} \sum_{i=1}^{m'} n_i.$$

Since  $\ell' = m' - 1$ ,

$$e' \leq k \left( \sum_{i=1}^{m'} n_i - \frac{1}{m'} \sum_{i=1}^{m'} n_i \right).$$

Substituting this in (22) and adding and subtracting  $k$  in the numerator of the left hand side, we have

$$\frac{nk\ell - (m-1)t}{mn - 1} < \frac{k \left( \sum_{i=1}^{m'} n_i - 1 \right) - k \left( \frac{1}{m'} \sum_{i=1}^{m'} n_i - 1 \right) - (m' - 1)t}{\sum_{i=1}^{m'} n_i - 1}.$$

Using the fact that  $k \geq m't$  and simplifying, we have

$$\begin{aligned}
 \frac{nk\ell - (m-1)t}{mn - 1} &< \frac{k \left( \sum_{i=1}^{m'} n_i - 1 \right) - m't \left( \frac{1}{m'} \sum_{i=1}^{m'} n_i - 1 \right) - (m' - 1)t}{\sum_{i=1}^{m'} n_i - 1} \\
 &= \frac{k \left( \sum_{i=1}^{m'} n_i - 1 \right) - t \left( \sum_{i=1}^{m'} n_i - m' \right) - (m' - 1)t}{\sum_{i=1}^{m'} n_i - 1}
 \end{aligned}$$

$$\begin{aligned}
 &= \frac{k \left( \sum_{i=1}^{m'} n_i - 1 \right) - t \left( \sum_{i=1}^{m'} n_i - 1 \right)}{\sum_{i=1}^{m'} n_i - 1} \\
 &= k - t.
 \end{aligned}$$

Substituting  $\ell = m - 1$  and cross-multiplying, we have

$$(m - 1)(nk - t) < (mn - 1)(k - t),$$

which simplifies to

$$-nk - mt < -k - mnt.$$

Thus,  $(n - 1)(mt) < (n - 1)k$ . Since  $n > 1$ , we have  $k > mt$  which is a contradiction.

Hence  $A$  is 1-balanced.  $\square$

Now, we are ready to show that if  $L$  is 1-balanced, then  $A$  is 1-balanced. We recall that in the generalized Cartesian product  $A = A_k(G_1, \dots, G_m; L)$ , the graphs  $G_i, i = 1, 2, \dots, m$  are 1-balanced and with the same number of vertices and edges; and  $k$  is any integer satisfying (12), i.e.,

$$\frac{t}{g(L)n} \leq k \leq \frac{mt}{g(L)},$$

where  $t = g(G_i), i = 1, 2, \dots, m$ .

**Theorem 13.** *If  $L$  is 1-balanced, then  $A$  is 1-balanced.*

**Proof.** Let  $g(L) = \frac{r}{s}$ . Since

$$\frac{t}{g(L)n} \leq k \leq \frac{mt}{g(L)},$$

substituting  $g(L) = \frac{r}{s}$ , we have

$$\frac{st}{rn} \leq k \leq \frac{mst}{r}, \quad \text{or} \quad \frac{st}{n} \leq kr \leq mst. \tag{23}$$

We first prove that  $A_{rs}$  is 1-balanced. By Corollary 4, if  $A_{rs}$  is 1-balanced, then  $A$  is 1-balanced. To prove  $A_{rs}$  is 1-balanced, we will prove that  $A_{rs}$  is an edge-disjoint union of  $r$  spanning 1-balanced connected subgraphs. Then, Corollary 3 will show that  $A_{rs}$  is 1-balanced.

Since  $L$  is 1-balanced of density  $\frac{r}{s}$ , by Theorem 2, there are  $r$  spanning trees  $T_1, T_2, \dots, T_r$  in  $L$  such that each edge of  $L$  appears in exactly  $s$  of the trees. Let us denote by  $B_e$  the  $k$ -regular bipartite graph that replaces the edge  $e \in L$  in  $A$ . For  $1 \leq j \leq r$ , let  $A_j$  be the generalized Cartesian product  $A_{kr}(G_1^s, \dots, G_m^s; T_j)$  using the  $kr$ -regular graphs  $B_e^r$  for each edge  $e$  in the tree  $T_j$ . Notice that  $G_i^s$  is 1-balanced by Corollary 4 and  $g(G_i^s) = st$  for  $i = 1, \dots, m$ . By (23), we have

$$\frac{g(G_i^s)}{n} \leq kr \leq mg(G_i^s).$$

By Theorem 12,  $A_j$  is 1-balanced for  $j = 1, 2, \dots, r$ .

**Claim.**  $A_{rs} = \cup_{j=1}^r A_j$ .

**Proof of Claim.** Each  $A_j, 1 \leq j \leq r$  has a copy of  $G_i^s$  for each  $i \in \{1, 2, \dots, m\}$ . Hence the edges of  $G_i$  appear  $rs$  times in  $\cup_{j=1}^r A_j$ .

Now, let  $e = (u, v)$  be an edge in  $L$ . In  $A_{rs}$ , we have  $B_e^{rs}$  between  $G_u$  and  $G_v$ . On the other hand,  $B_e^r$  appears in exactly  $s$  of  $A_1, A_2, \dots, A_r$  since  $e$  appears in exactly  $s$  of  $T_1, T_2, \dots, T_r$ . Thus we can find  $B_e^{rs}$  in  $\cup_{j=1}^r A_j$ . Hence the claim.

Thus  $A_{rs}$  is 1-balanced and the theorem follows.  $\square$

**Corollary 14.** *If connected graphs  $G_1$  and  $G_2$  are both 1-balanced, then the Cartesian product  $G_1 \times G_2$  is 1-balanced.*

**Proof.** There are two ways to view  $G_1 \times G_2$  as a generalized Cartesian product.  $G_1 \times G_2 = A_1(G_1, G_1, \dots, G_1; G_2)$  with suitable choices of the bipartite graphs  $B_{ij}$ . Similarly,  $G_1 \times G_2 = G_2 \times G_1 = A_1(G_2, G_2, \dots, G_2; G_1)$  with suitable choices of the bipartite graphs  $B_{ij}$ .

We first prove that either

$$\frac{g(G_1)}{|V(G_1)|g(G_2)} \leq 1, \tag{24}$$

or

$$\frac{g(G_2)}{|V(G_2)|g(G_1)} \leq 1 \tag{25}$$

holds. Suppose both (24) and (25) do not hold. Then we have

$$g(G_1) > |V(G_1)|g(G_2) > |V(G_1)||V(G_2)|g(G_1),$$

a contradiction since  $|V(G_1)||V(G_2)| \geq 1$ .

Now, if (24) holds, then by Theorem 13 with  $k = 1$  (noting that  $k = 1$  satisfies (12)),  $A_1(G_1, G_1, \dots, G_1; G_2) = G_1 \times G_2$  is 1-balanced. Similarly, if (25) holds, then by Theorem 13 with  $k = 1$ ,  $A_1(G_2, G_2, \dots, G_2; G_1) = G_1 \times G_2$  is 1-balanced.  $\square$

### Appendix

**(Sufficiency of  $L$  strictly balanced)** We note that  $N_\alpha = 0$  for all constant labelings  $\alpha$ . For a contradiction, suppose  $L$  is strictly balanced while there is a non-constant, non-negative, integer-valued function  $\alpha$  on  $V(L)$  with  $N_\alpha \geq 0$ . Choose non-constant  $\alpha_0$  such that  $N_{\alpha_0} \geq 0$  and  $s = \max_{1 \leq i \leq m} \alpha_0(v_i)$  is as small as possible. Since  $\alpha_0$  is not constant, there is a  $j \in \{1, 2, \dots, m\}$  such that  $\alpha_0(v_j) < s$ . Then the integer  $s \geq 1$  since  $\alpha_0(v_i) \geq 0$ .

Let  $S := \{v_i : \alpha_0(v_i) = s\}$ ; by definition of  $s$  and  $j$ ,  $S \neq \emptyset, V$ . Consider the function  $\alpha'_0$  defined by  $\alpha'_0(v_i) = \alpha_0(v_i)$  if  $v_i \notin S$  and  $\alpha_0(v_i) - 1$  if  $v_i \in S$ . Thus  $\max_{1 \leq i \leq m} \alpha'_0(v_i) < s$ .

We claim that  $N_{\alpha'_0} > N_{\alpha_0}$ , and thus  $\alpha'_0$  is non-constant.

Let  $L' := L[S]$ , and denote  $m' := |V(L')| = |S|$  and  $\ell' := |E(L')|$ . Exactly as in the case of non-strictly balanced,

$$N_{\alpha'_0} - N_{\alpha_0} = m' \left( -\frac{\ell'}{m'} + \frac{\ell}{m} \right).$$

But this is greater than zero either because  $L$  is strictly balanced and so  $\frac{\ell'}{m'} = b(L') < b(L) = \frac{\ell}{m}$  or because  $\ell' = 0$ .

Thus  $N_{\alpha'_0} > N_{\alpha_0} \geq 0$ , so  $\alpha'_0$  is not constant. This is a contradiction to the choice of  $\alpha_0$  and the minimality of  $s$ . The contradiction proves sufficiency.

**(Necessity of  $L$  strictly balanced)** Suppose  $N_\alpha < 0$  for all non-constant labelings  $\alpha$ . Let  $L'$  be any non-trivial vertex-induced subgraph of  $L$ ,  $L' \neq L$ , and suppose  $L'$  has  $m'$  vertices and  $\ell'$  edges. Define  $\alpha$  on  $V(L)$  by letting  $\alpha(v) = 1$  if  $v \in V(L')$  and 0 if  $v \notin V(L')$ . Then  $\alpha$  is not constant, so

$$\frac{1}{m} \sum_{r=1}^m \alpha(v_r) = \frac{m'}{m},$$

and

$$\begin{aligned} 0 > N_\alpha &= \sum_{v_i v_j \in E(L')} \left( 1 - \frac{m'}{m} \right) + \sum_{v_i v_j \notin E(L')} \left( -\frac{m'}{m} \right) \\ &= \ell' - \frac{m' \ell'}{m} - \frac{m' \ell}{m} + \frac{m' \ell'}{m} \\ &= \ell' - \frac{m' \ell}{m} \\ &= m' \left( \frac{\ell'}{m'} - \frac{\ell}{m} \right). \end{aligned}$$

Since  $m' > 0$ , we have  $\frac{\ell'}{m'} < \frac{\ell}{m}$  (i.e.,  $b(L') < b(L)$ ), so  $L$  is strictly balanced.

### References

- [1] A. Brodera, R. Kumar, F. Maghoula, P. Raghavanb, S. Rajagopalanb, R. Statac, A. Tomkinsb, J. Wienerc, Graph structure in the Web, *Computer Networks* 33 (2000) 309–320.
- [2] P.A. Catlin, J.W. Grossman, A.M. Hobbs, H.-J. Lai, Fractional arboricity, strength and principal partitions in graphs and matroids, *Discrete Appl. Math.* 40 (1992) 285–302.
- [3] R. Diestel, *Graph Theory*, third ed., Springer, New York, 2005.
- [4] P. Erdős, A. Renyi, On random graphs I, *Publ. Math. Debrecen* 6 (1959) 290–297.
- [5] P. Erdős, A. Renyi, On the evolution of random graphs, *Publ. Math. Hung. Acad. Sci.* 5 (1960) 17–61.
- [6] G.W. Flake, S. Lawrence, C.L. Giles, Efficient Identification of Web Communities, in: *Sixth ACM SIGKDD International Conference on Knowledge Discovery and Data Mining*, ACM Press, 2000, pp. 150–160.
- [7] D. Gusfield, Connectivity and edge-disjoint spanning trees, *Inform. Process. Lett.* 16 (1983) 87–89.

- [8] G. Hardy, J.E. Littlewood, G. Polya, *Inequalities*, Cambridge University Press, Cambridge, 1952.
- [9] Y. Hirate, S. Kato, H. Yamana, Web structure in 2005, in: *Algorithms and Models for the Web-Graph: Fourth International Workshop, WAW 2006, Banff, Canada, November 30–December 1, 2006*, Springer-Verlag, Berlin, Heidelberg, 2008, pp. 36–46.
- [10] A.M. Hobbs, Network survivability, in: J.G. Michaels, K.H. Rosen (Eds.), *Applications of Discrete Mathematics*, McGraw-Hill, Inc., New York, 1991, pp. 332–353.
- [11] A.M. Hobbs, H.-J. Lai, H. Lai, G. Weng, Uniformly dense generalized prisms over graphs, *Cong. Numer.* 91 (1992) 99–105.
- [12] T. Luczak, A. Ruciński, Convex hulls of dense balanced graphs, *J. Comput. Appl. Math.* 41 (1992) 205–213.
- [13] H. Narayanan, M.N. Vartak, An elementary approach to the principal partition of a matroid, *Trans. IECE Japan E64* (1981) 227–234.
- [14] H. Narayanan, M.N. Vartak, On molecular and atomic matroids, in: S.B. Rao (Ed.), *Combinatorics and Graph Theory (Proc., Calcutta, 1980)*, in: *Lecture Notes in Math.*, vol. 885, Springer-Verlag, Berlin, 1981, pp. 358–364.
- [15] J.G. Oxley, *Matroid Theory*, Oxford University Press, New York, 1992.
- [16] C. Payan, Graphes équilibrés et arboricité rationnelle, *European J. Combin.* 7 (1986) 263–270.
- [17] S.G. Penrice, Balanced graphs and network flows, *Networks* 29 (1997) 77–80.
- [18] B.L. Piazza, R.D. Ringeisen, Connectivity of generalized prisms over  $G$ , *Discrete Appl. Math.* 30 (1991) 229–233.
- [19] A. Ruciński, A. Vince, Strongly balanced graphs and random graphs, *J. Graph Theory* 10 (1986) 251–264.
- [20] N. Tomizawa, Strongly irreducible matroids and principal partition of a matroid into strongly irreducible minors, *Elect. and Comm. in Japan* 59A (2) (1976) 1–10.
- [21] N. Veerapandiyan, S. Arumugam, On balanced graphs, *Ars Combin.* 32 (1991) 221–223.